

Graphs, DFS, BFS

SOI Camp Ftan -- Advanced track

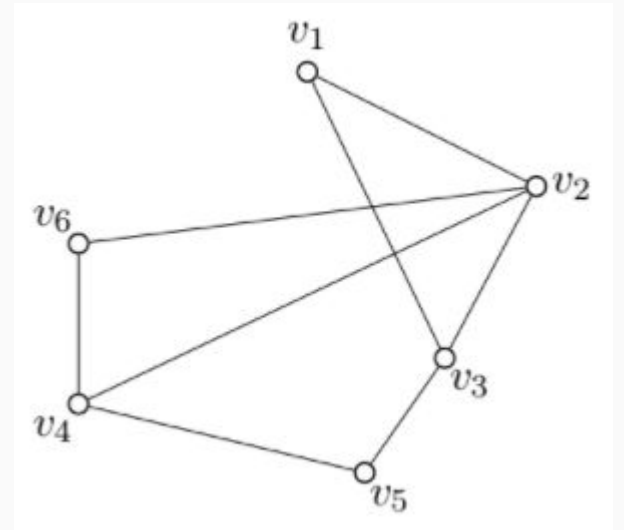
Jakub Závodný

12.2.2018



Graphs

Graphs



Graphs

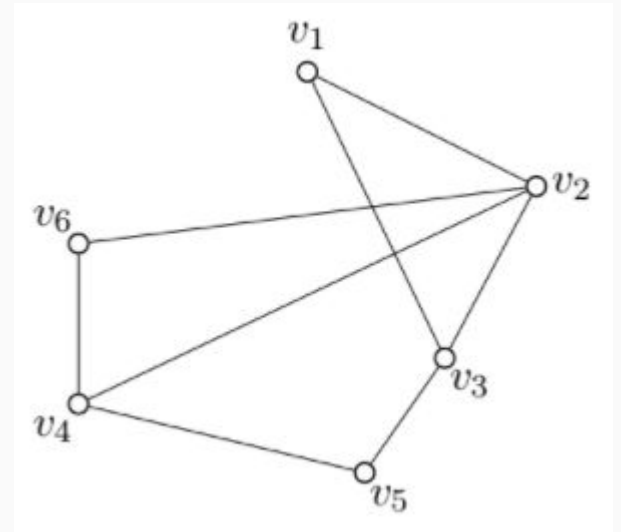
Graph = (V, E)

V = set of vertices

E = set of edges (pairs of vertices)

$N = |V|$ = number of vertices

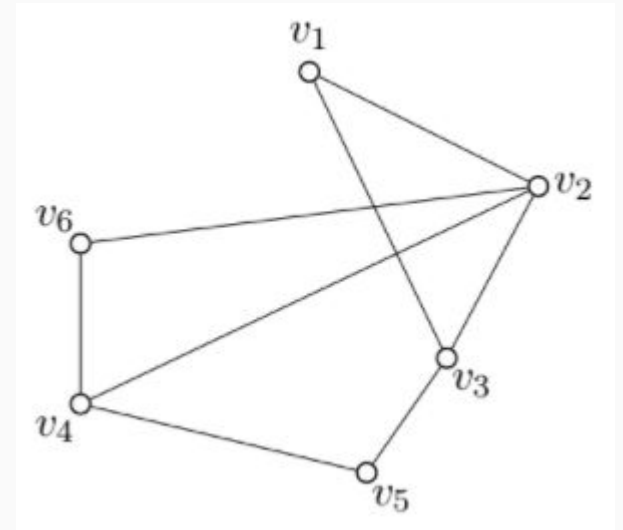
$M = |E|$ = number of edges



Graph Representations

$V = \{1, 2, 3, 4, 5, 6\}$

$E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 6),$
 $(3, 5), (4, 5), (4, 6)\}$

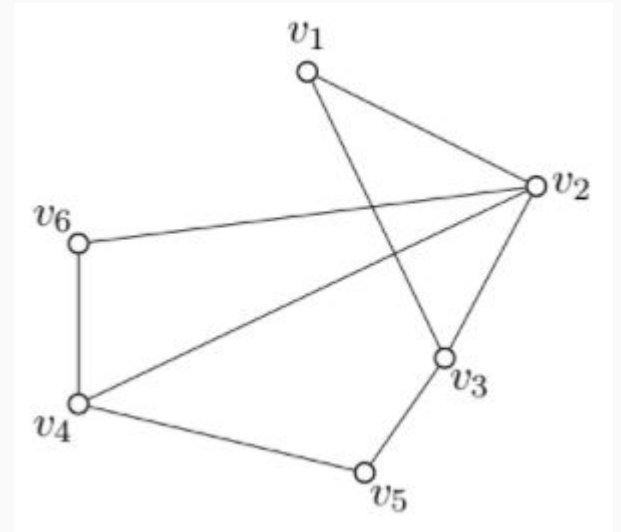


Graph Representations

$$V = \{1, 2, 3, 4, 5, 6\}$$

$$n = 6$$

$$E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 6), \\ (3, 5), (4, 5), (4, 6)\}$$



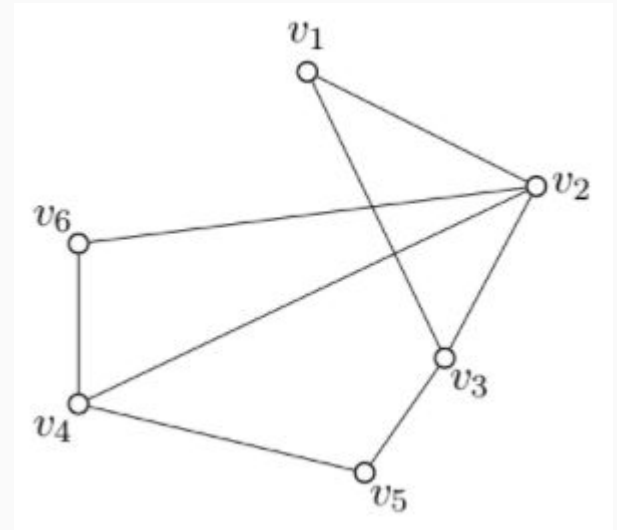
Graph Representations

~~$V = \{1, 2, 3, 4, 5, 6\}$~~

$n = 6$

$\text{name} = \{\text{"Zurich"}, \text{"Basel"}, \text{"Zug"}, \dots\}$

$E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 6),$
 $(3, 5), (4, 5), (4, 6)\}$

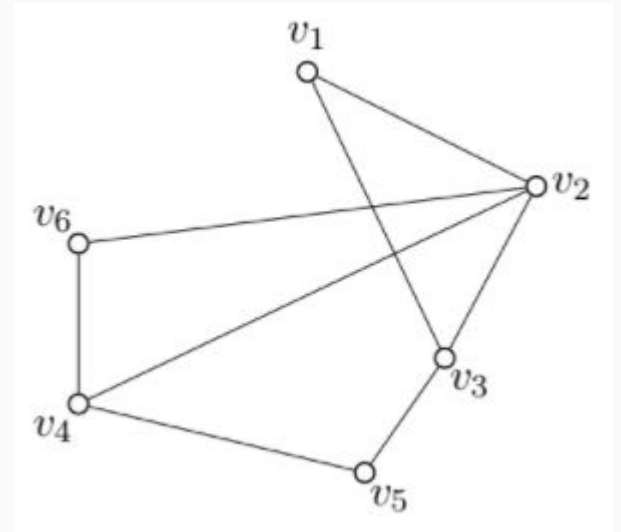


Graph Representations

$$V = \{1, 2, 3, 4, 5, 6\}$$

$$n = 6$$

$$E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 6), \\ (3, 5), (4, 5), (4, 6)\}$$



Graph Representations

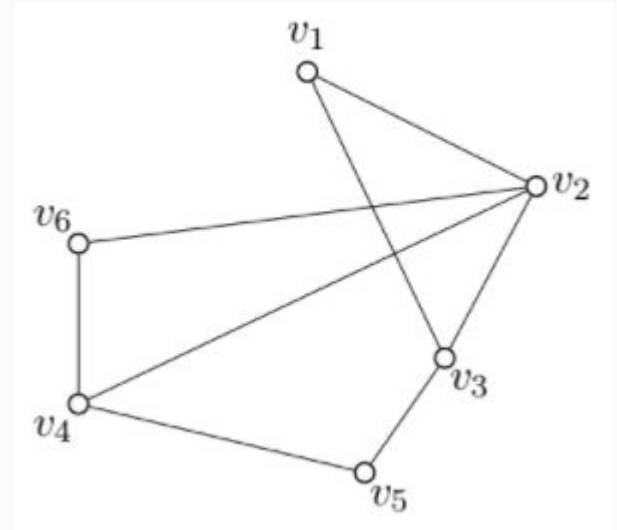
~~$V = \{1, 2, 3, 4, 5, 6\}$~~

$n = 6$

$E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 6),$
 $(3, 5), (4, 5), (4, 6)\}$

$e = \text{vector}\langle \text{pair}\langle \text{int}, \text{int} \rangle \rangle$

List of edges



Graph Representations

~~$V = \{1, 2, 3, 4, 5, 6\}$~~

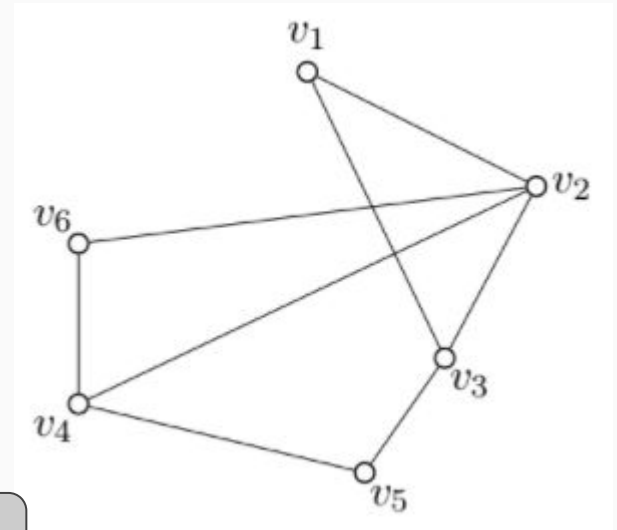
$n = 6$

$E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 6),$
 $(3, 5), (4, 5), (4, 6)\}$

$A = \{\{2,3\}, \{1,3,4,6\}, \{1,2,5\}, \{2,5,6\}, \{3,4\}, \{2,6\}\}$

`a = vector<vector<int>>`

List of lists of neighbours ("adjacency list")



Graph Representations

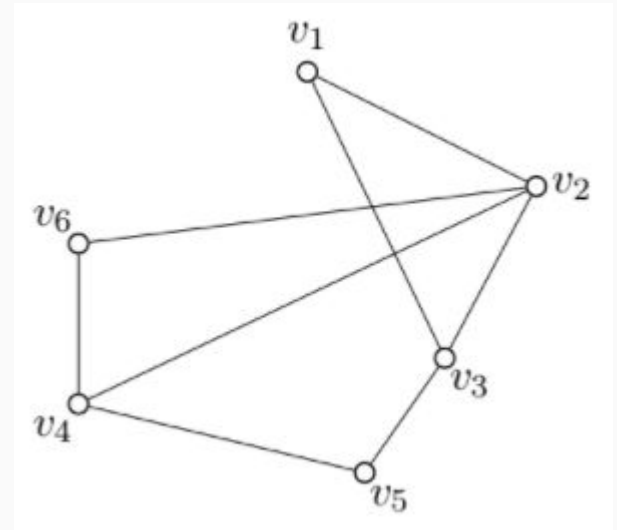
$E = \{(1, 2), (1, 3), (2, 3), (2, 4), (2, 6),$
 $(3, 5), (4, 5), (4, 6)\}$

$A = \{\{2,3\}, \{1,3,4,6\}, \{1,2,5\}, \{2,5,6\}, \{3,4\}, \{2,6\}\}$

$A' = \{\{0,1,1,0,0,0\},$
 $\{1,0,1,1,0,1\},$
 $\{1,1,0,0,1,0\}, \dots\}$

`a = vector<vector<bool>>`

Adjacency matrix.



Graph Representations

List of edges:

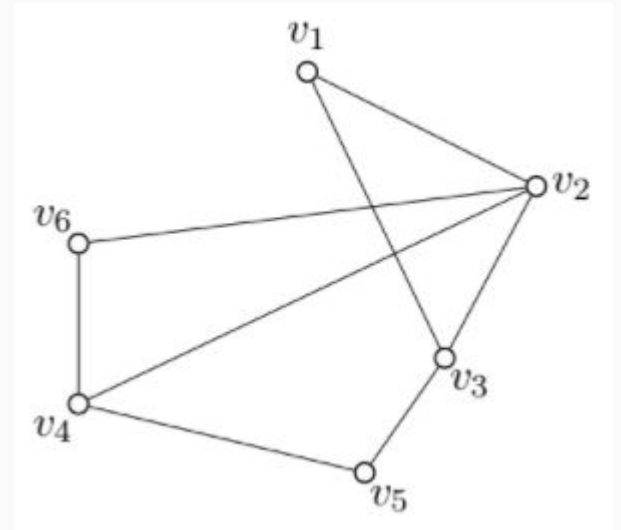
```
e = vector<pair<int, int>>
```

Adjacency lists:

```
a = vector<vector<int>>
```

Adjacency matrix:

```
a = vector<vector<bool>>
```



Graph Representations: Weighted Graphs

List of edges:

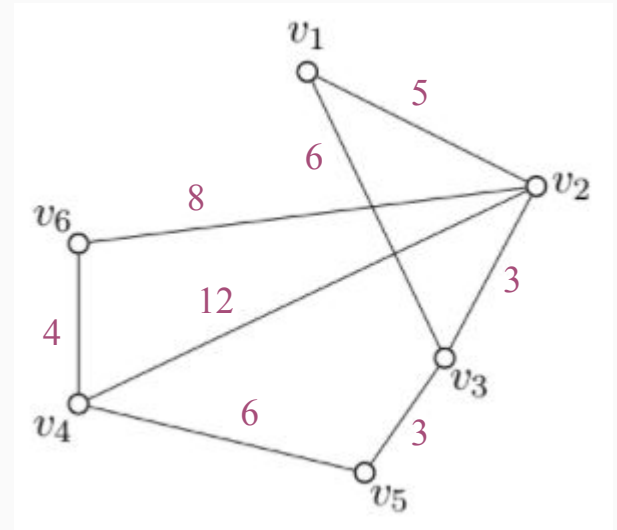
```
e = vector<pair<pair<int, int>, int>>
```

Adjacency lists:

```
a = vector<vector<pair<int, int>>>
```

Adjacency matrix:

```
a = vector<vector<int>>
```



Graph Representations: Weighted Graphs

List of edges:

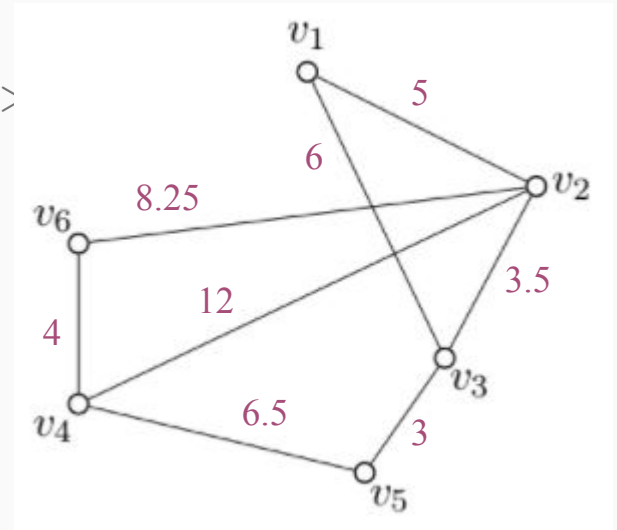
```
e = vector<pair<pair<int, int>, float>>
```

Adjacency lists:

```
a = vector<vector<pair<int, float>>>
```

Adjacency matrix:

```
a = vector<vector<float>>
```



Graph Representations

List of edges:

```
e = vector<pair<int, int>>
```

Size $O(|E|)$

Adjacency lists:

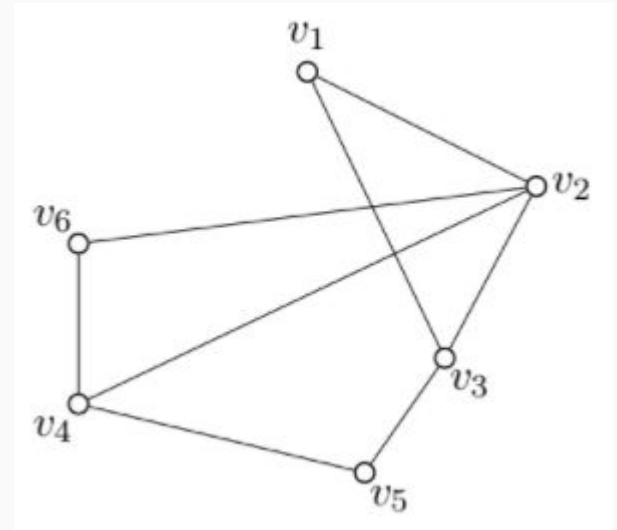
```
a = vector<vector<int>>
```

Size $O(|V| + |E|)$

Adjacency matrix:

```
a = vector<vector<bool>>
```

Size $O(|V|^2)$



Graph Representations

List of edges:

```
e = vector<pair<int, int>>
```

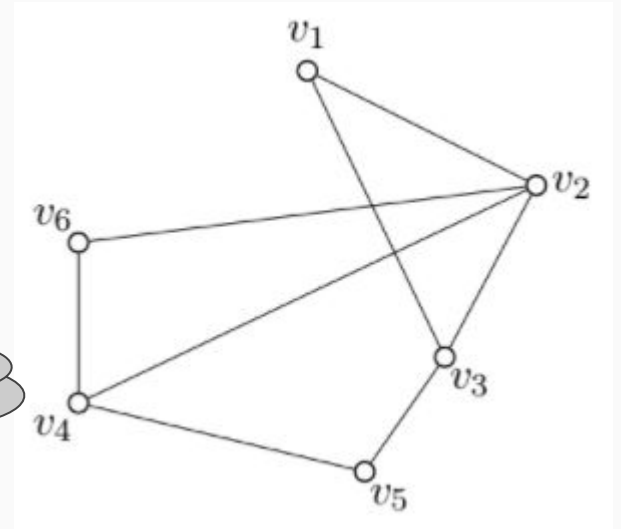
Adjacency lists:

```
a = vector<vector<int>>
```

Adjacency matrix:

```
a = vector<vector<bool>>
```

Which one to use?



Graph Representations

List of edges:

```
e = vector<pair<int, int>>
```

Adjacency lists:

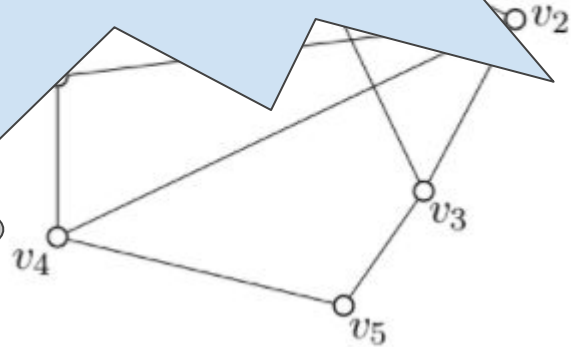
```
a = vector<vector<int>>
```

Adjacency matrix:

```
a = vector<vector<bool>>
```

Depends on the situation.

Which one to use?



Graph Representations

List of edges:

```
e = vector<pair<int, int>>
```

Adjacency lists:

```
a = vector<vector<int>>
```

Adjacency matrix:

```
a = vector<vector<bool>>
```

Depends on the situation.

There are many other variations.

Graph Representations

List of edges:

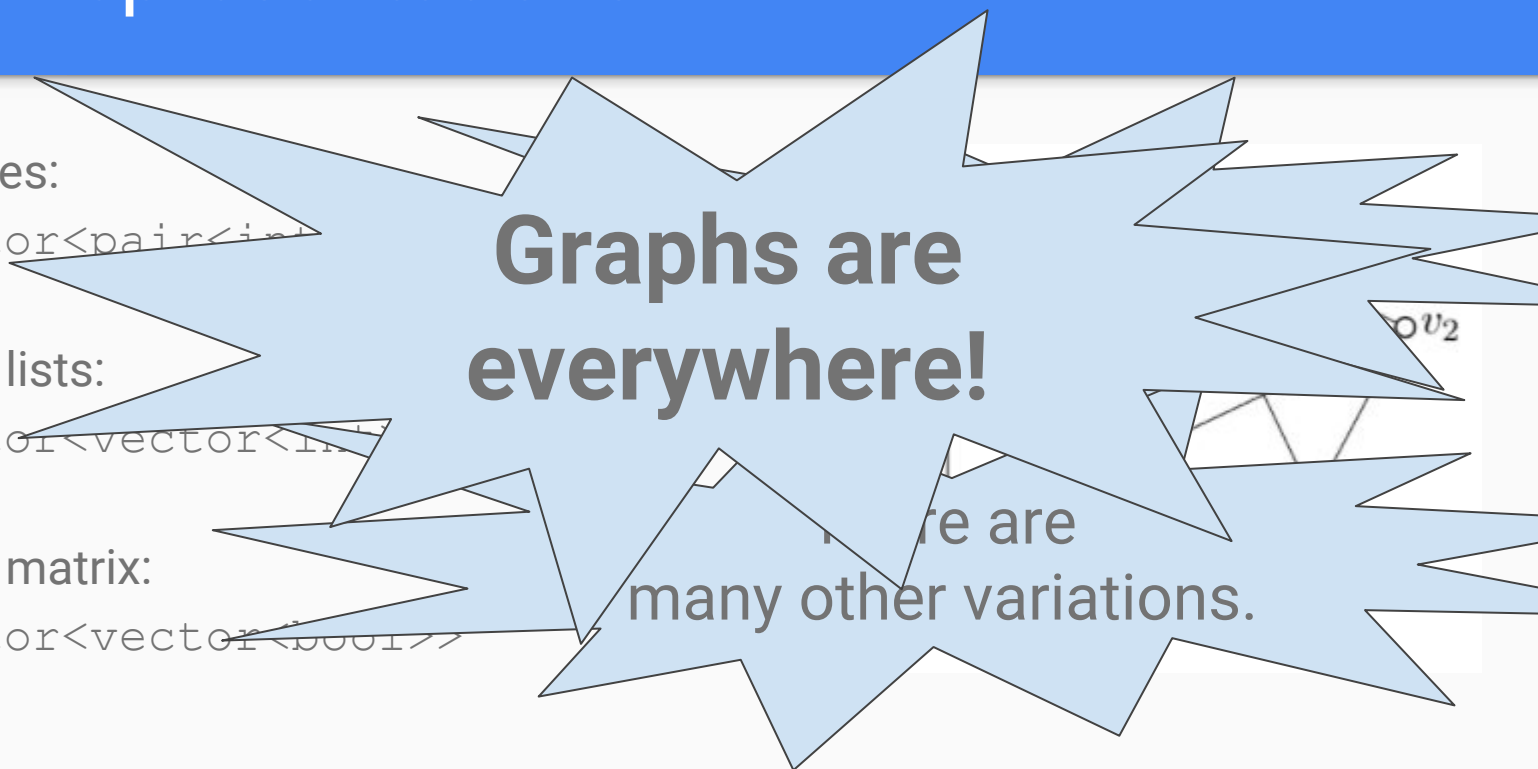
```
e = vector<pair<int, int>>
```

Adjacency lists:

```
a = vector<vector<int>>
```

Adjacency matrix:

```
a = vector<vector<bool>>
```



Graphs are everywhere!

There are many other variations.

Graph Representations

Maze:

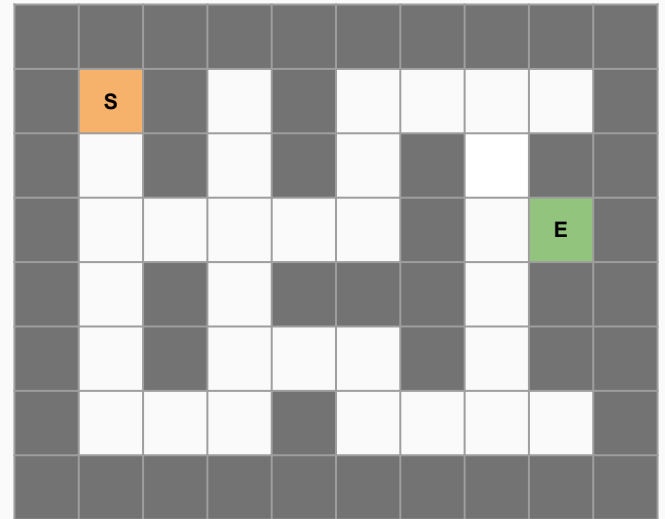
Is an implicit graph.

```
m = vector<vector<char>>
```

Vertices are all fields (i,j) with $m[i][j] == '.'$
(or 'S' or 'E')

Neighbours of (i,j) are $(i,j+1)$, $(i,j-1)$, $(i+1,j)$, $(i-1,j)$
when they exist.

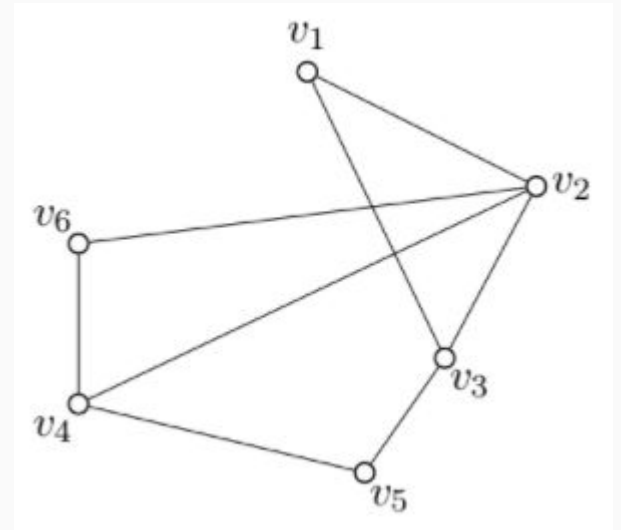
We do not need to “store” the edges!



Searching Graphs

Depth-first Search

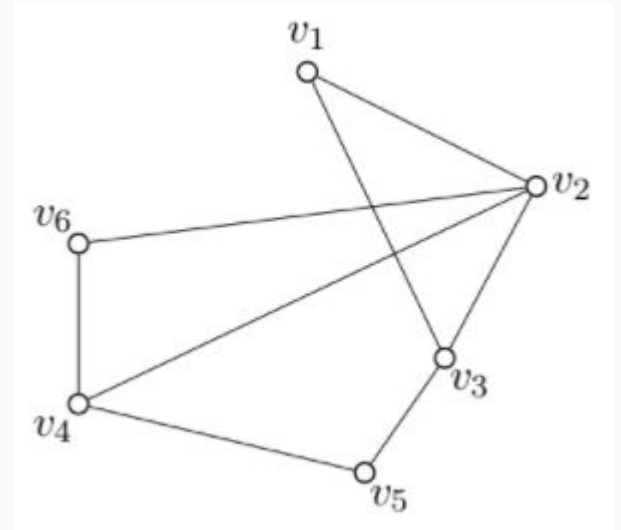
Breadth-first Search



Searching Graphs:

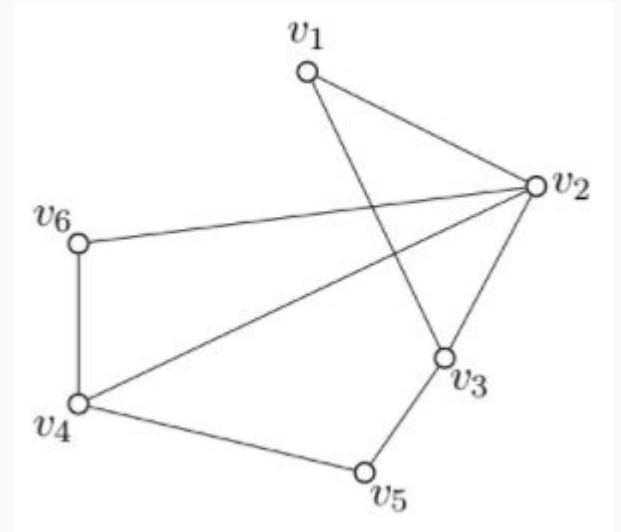
```
mark all vertices not visited  
mark start as visited  
vertices to look at = {start}
```

```
while we still have vertices to look at {  
  take one of them  
  for all its unvisited neighbors n {  
    mark n visited  
    put n into vertices to look at  
  }  
}
```



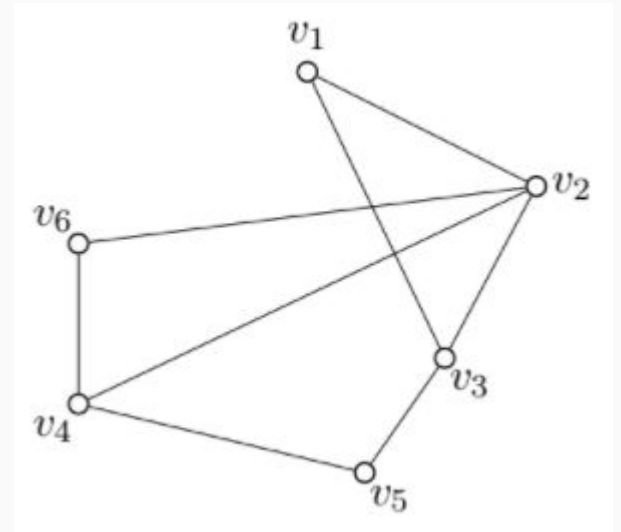
Searching Graphs: DFS

```
vector<int> stack;  
visited[start] = true; stack.push_back(start);  
while !stack.empty() {  
    v = stack.pop()  
    for (int n : a[v]) {  
        if (!visited[n]) {  
            visited[n] = true;  
            stack.push_back(n);  
        }  
    }  
}
```



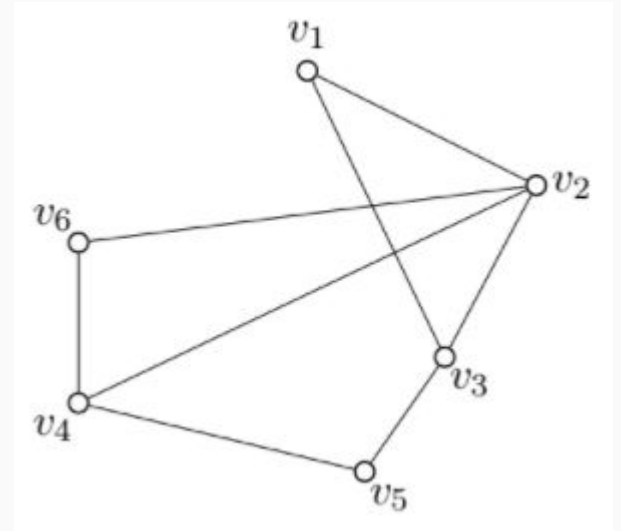
Searching Graphs: BFS

```
queue<int> q;  
visited[start] = true; q.push_back(start);  
while !q.empty() {  
    v = q.pop_front()  
    for (int n : a[v]) {  
        if (!visited[n]) {  
            visited[n] = true;  
            q.push_back(n);  
        }  
    }  
}
```



Searching Graphs: Dijkstra's Algorithm

```
priority_queue<float, int> q;  
distance[start] = 0; q.push_back((0, start));  
while !q.empty() {  
    (d, v) = q.top()  
    for (int n : a[v]) {  
        if (there is a shortcut to n via v) {  
            update distance[n]  
            q.push_back(distance[n], n);  
        }  
    }  
}
```

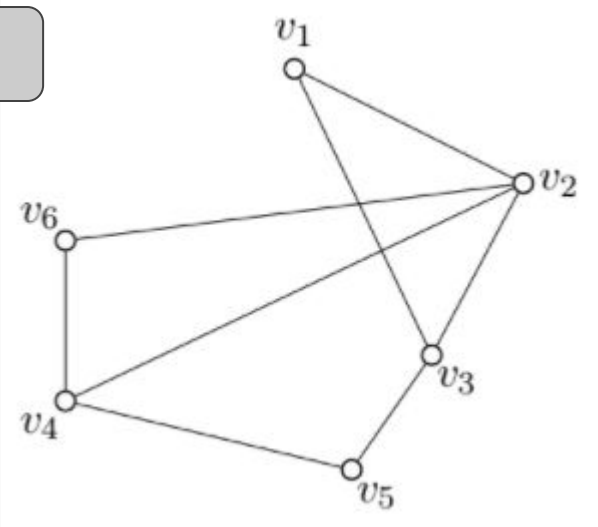


Searching Graphs:

mark all vertices not visited
mark start as visited
vertices to look at = {start}

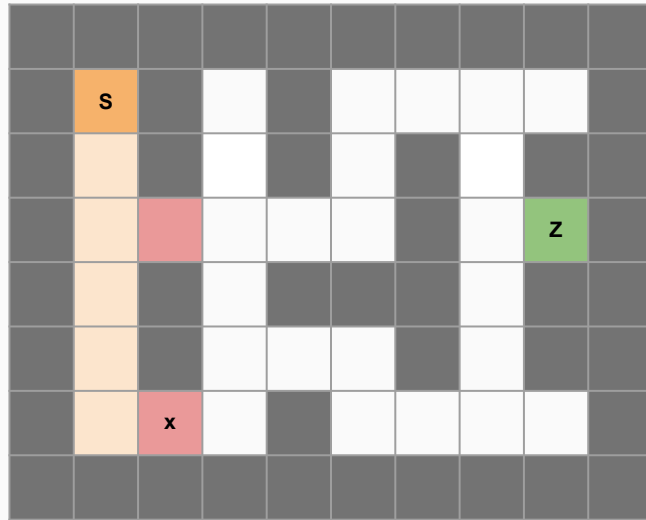
```
vector<bool> visited;
```

```
while we still have vertices to look at {  
  take one of them  
  for all its unvisited neighbors n {  
    mark n visited  
    put n into vertices to look at  
  }  
}
```



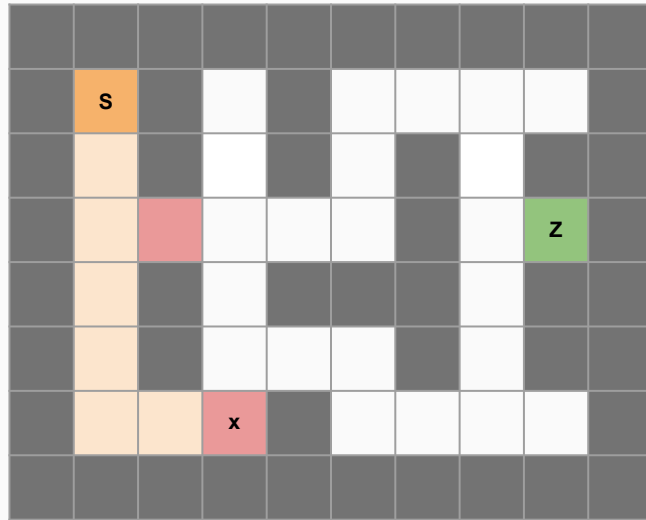
DFS in a Maze

```
stack = [  
    (3,2)  
]
```



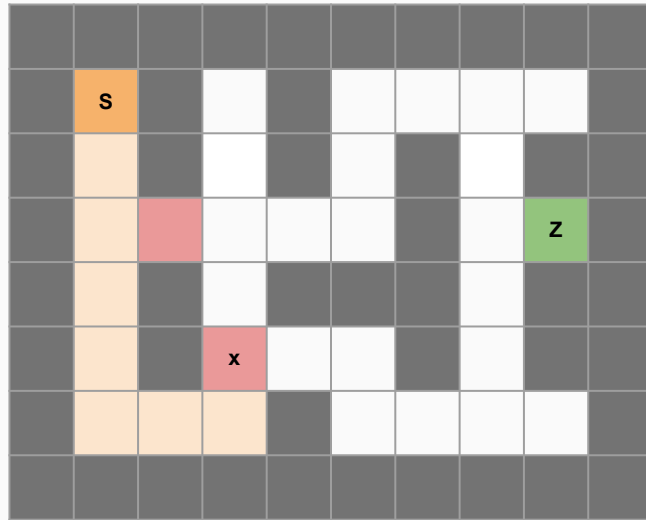
DFS in a Maze

```
stack = [  
    (3,2)  
]
```



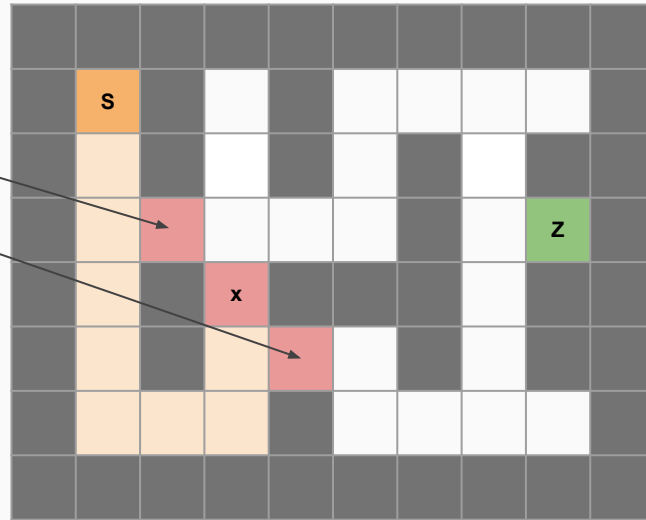
DFS in a Maze

```
stack = [  
    (3,2)  
]
```



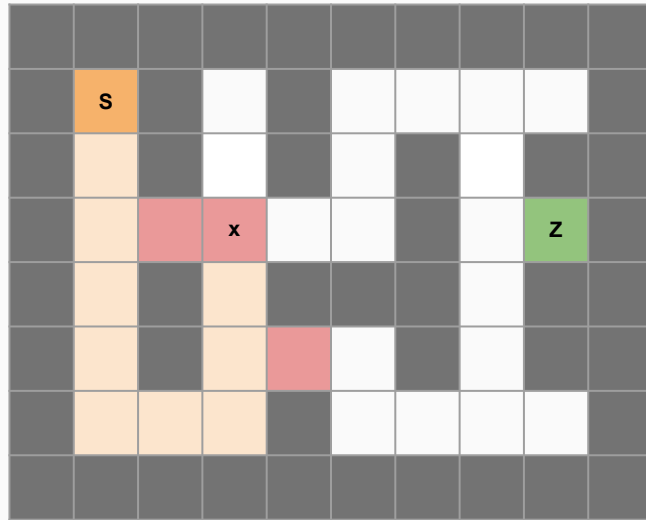
DFS in a Maze

```
stack = [  
  (3, 2),  
  (5, 4)  
]
```



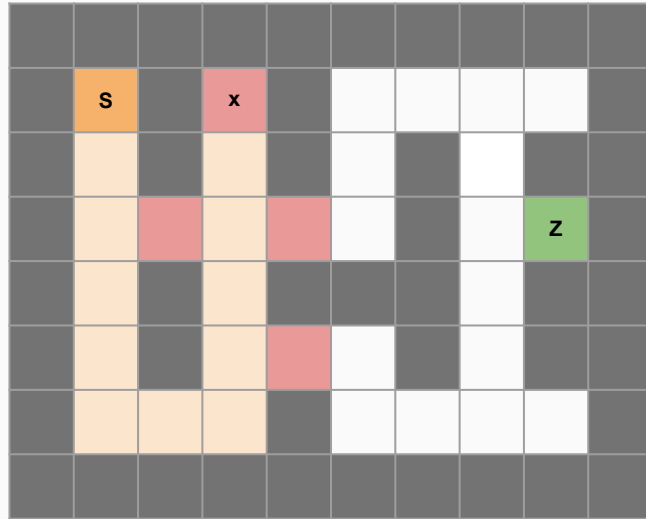
DFS in a Maze

```
stack = [  
  (3,2),  
  (5,4)  
]
```



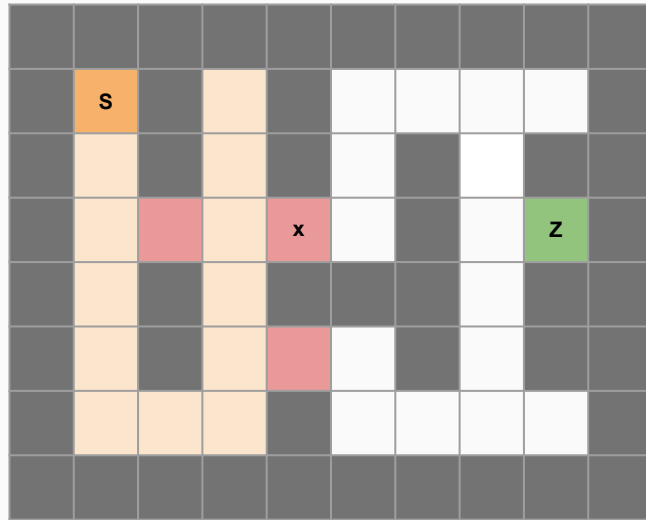
DFS in a Maze

```
stack = [  
  (3,2),  
  (5,4),  
  (3,4)  
]
```



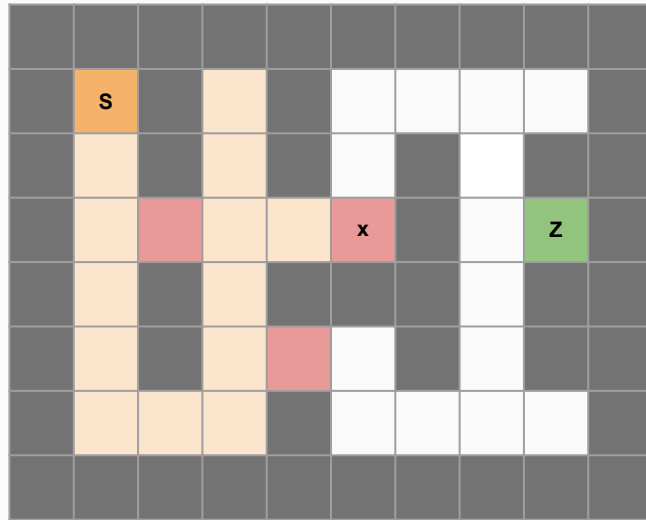
DFS in a Maze

```
stack = [  
  (3,2),  
  (5,4)  
]
```



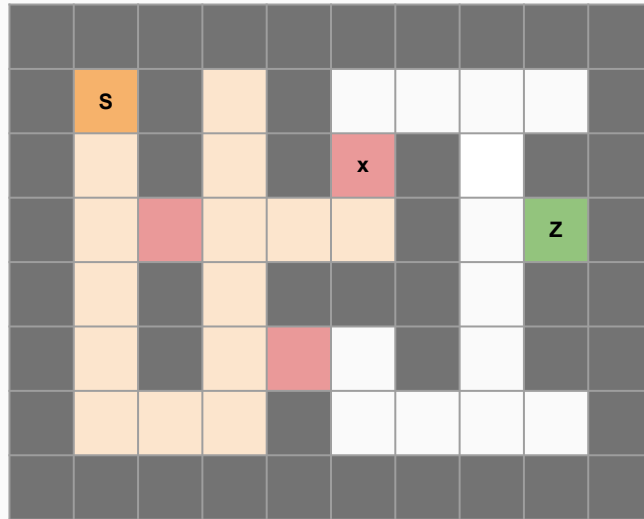
DFS in a Maze

```
stack = [  
  (3,2),  
  (5,4)  
]
```



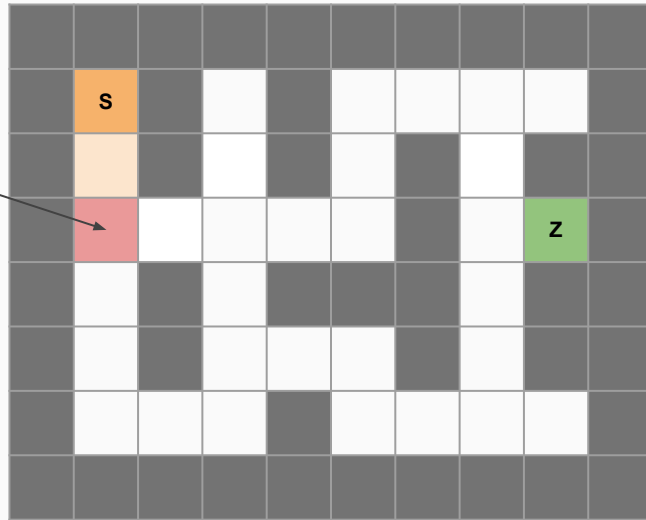
DFS in a Maze

```
stack = [  
  (3,2),  
  (5,4)  
]
```



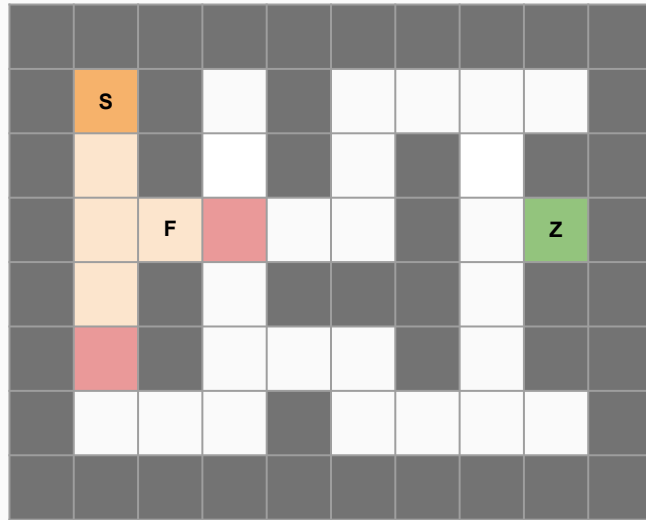
BFS in a Maze

```
queue = [  
  (3,1)  
]
```



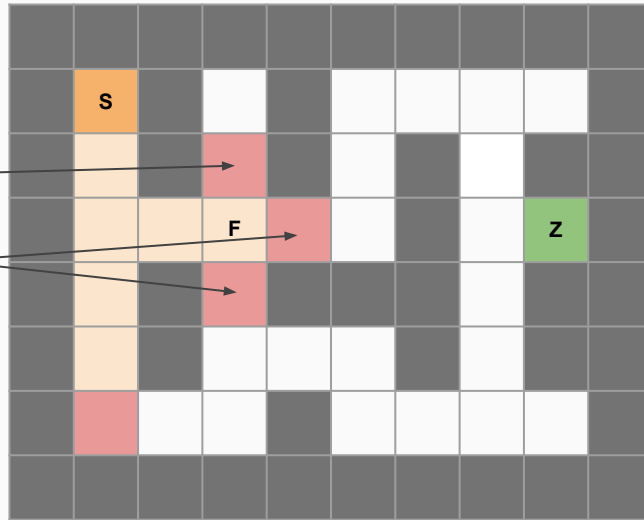
BFS in a Maze

```
queue = [  
  (3, 2),  
  (5, 1),  
  (3, 3)  
]
```



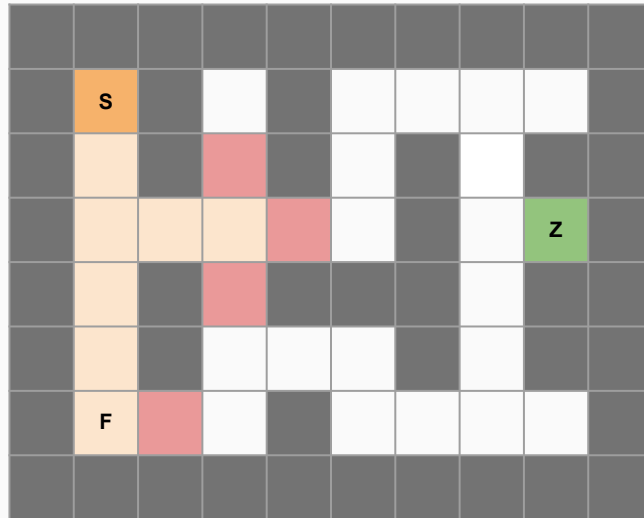
BFS in a Maze

```
queue = [  
  (3, 3),  
  (6, 1),  
  (2, 3),  
  (4, 3),  
  (3, 4),  
]
```



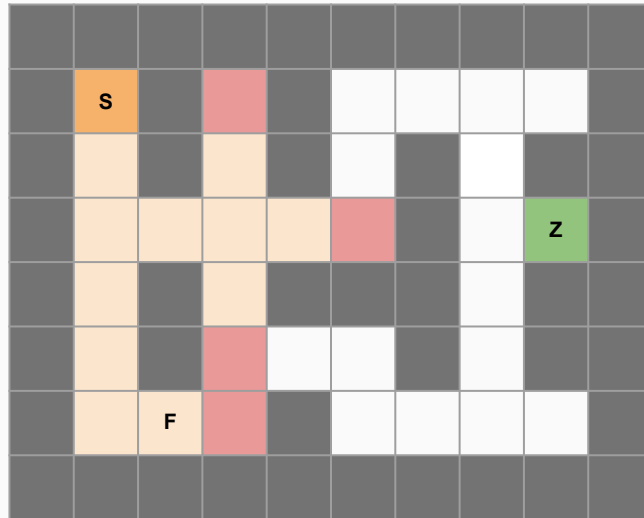
BFS in a Maze

```
queue = [  
  (6, 1),  
  (2, 3),  
  (4, 3),  
  (3, 4),  
  (6, 2),  
]
```



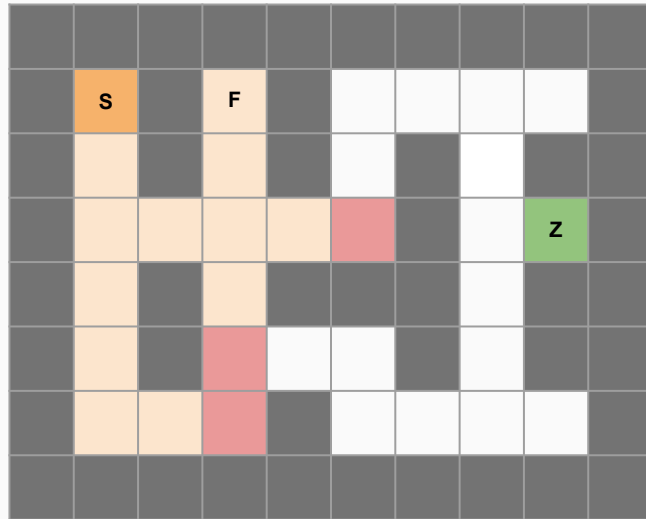
BFS in a Maze

```
queue = [  
  (6, 2),  
  (1, 3),  
  (5, 3),  
  (3, 5),  
  (6, 3)  
]
```



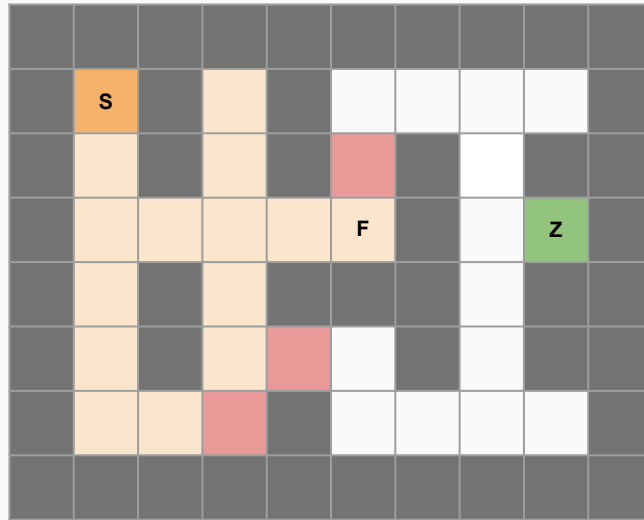
BFS in a Maze

```
queue = [  
  (1, 3),  
  (5, 3),  
  (3, 5),  
  (6, 3)  
]
```



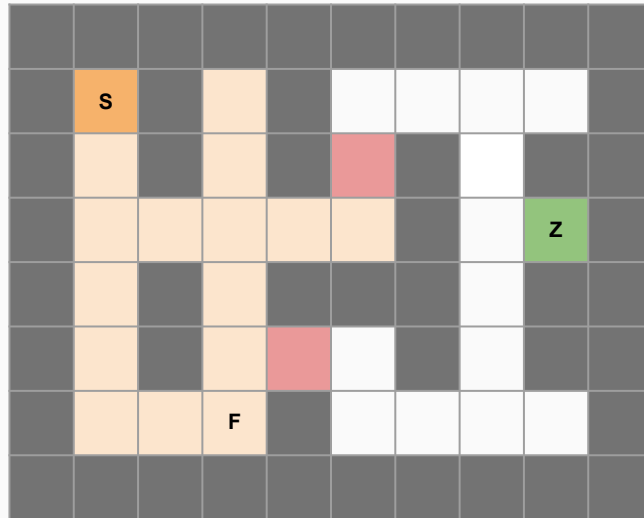
BFS in a Maze

```
queue = [  
  (3, 5),  
  (6, 3),  
  (5, 4),  
  (2, 5)  
]
```



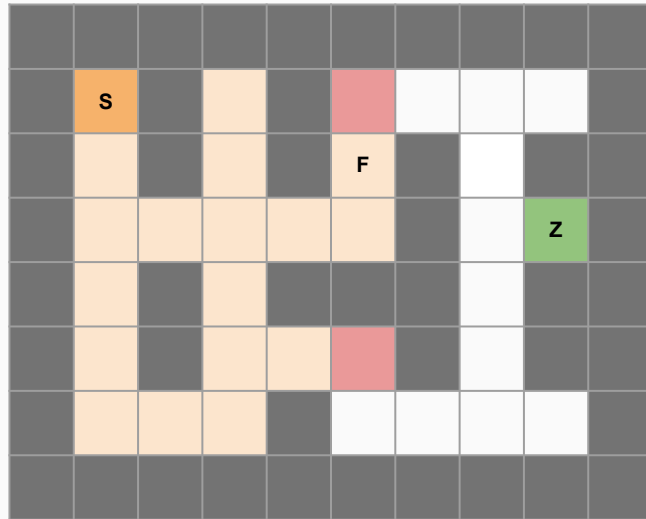
BFS in a Maze

```
queue = [  
  (6,3),  
  (5,4),  
  (2,5)  
]
```



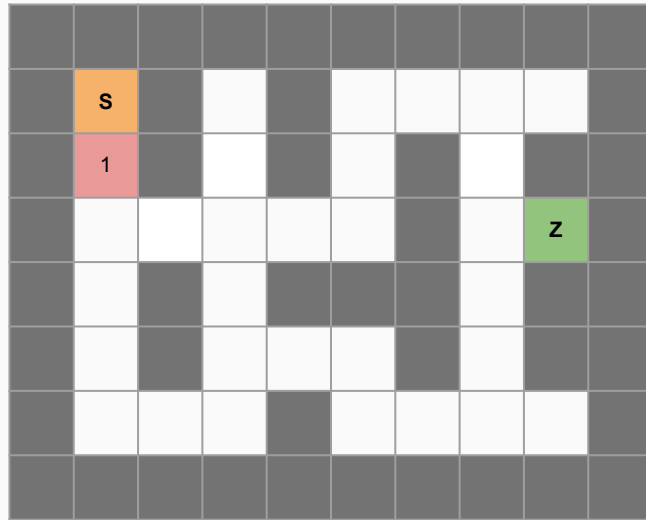
BFS in a Maze

```
queue = [  
  (2, 5),  
  (5, 5),  
  (1, 5)  
]
```



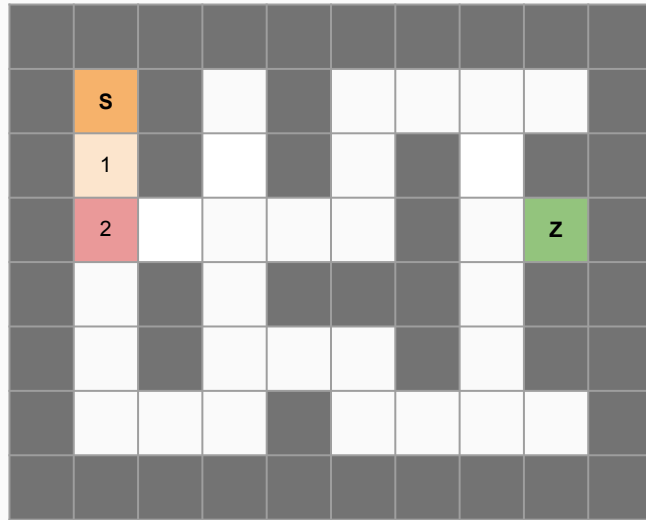
BFS in a Maze

```
queue = [  
    (2,1)  
]
```



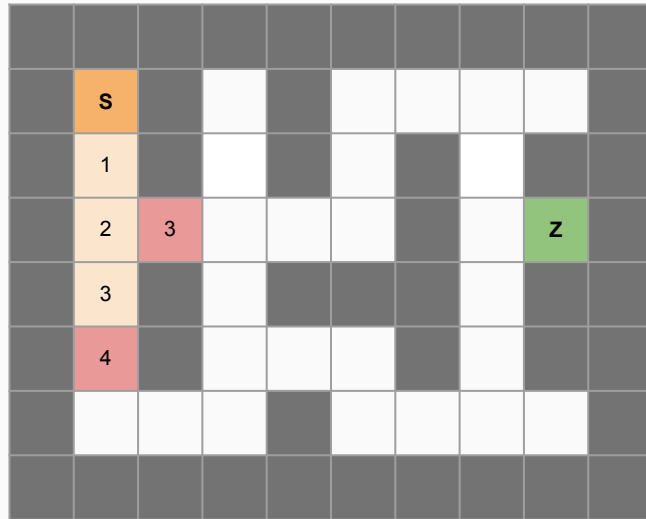
BFS in a Maze

```
queue = [  
    (3,1)  
]
```



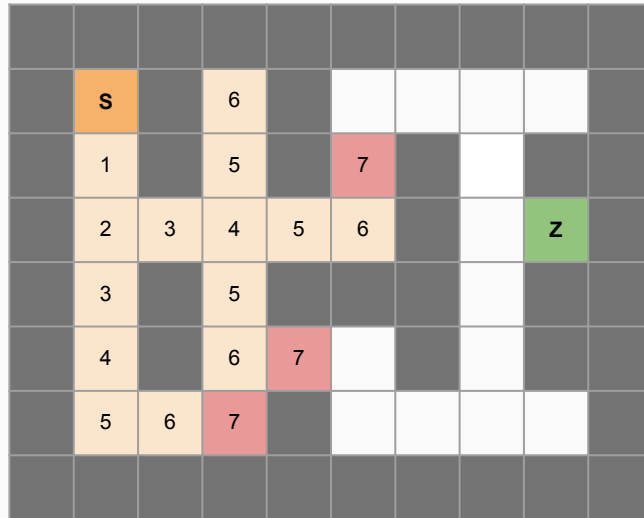
BFS in a Maze

```
queue = [  
  (3,2),  
  (5,1)  
]
```



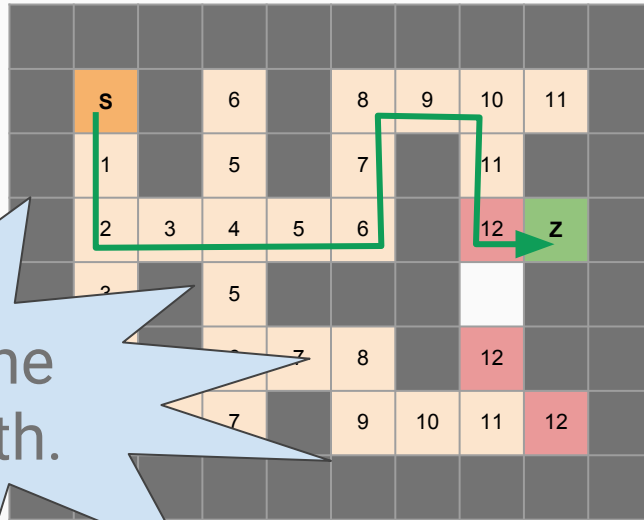
BFS in a Maze

```
queue = [  
  (6, 3),  
  (5, 4),  
  (2, 5)  
]
```



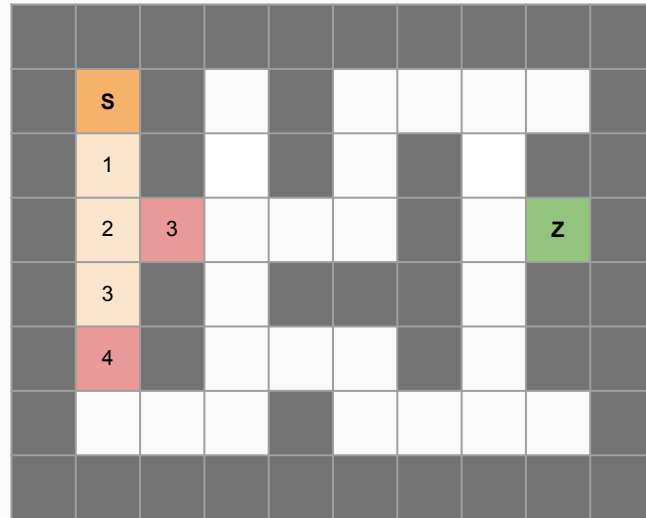
BFS in a Maze

```
queue = [  
  (5, 7),  
  (6, 8),  
  (3, 7)  
]
```

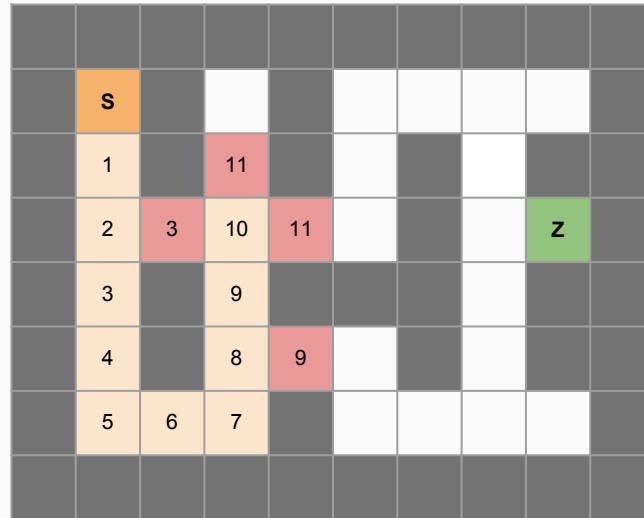


BFS finds the shortest path.

DFS in a Maze

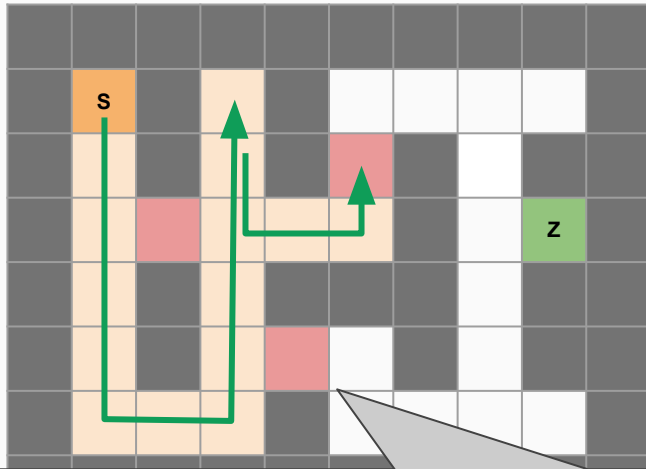


DFS in a Maze



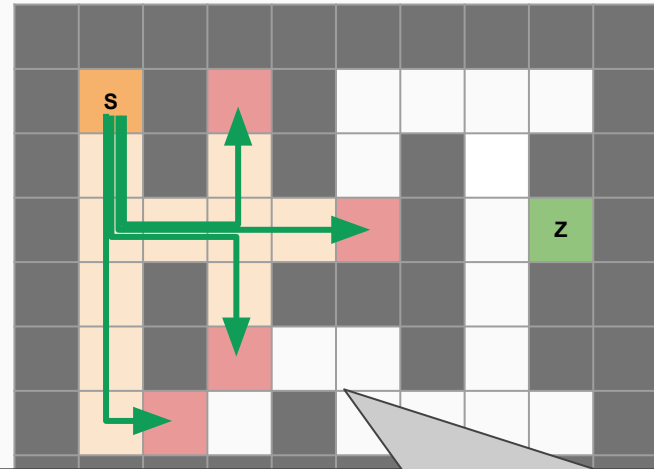
DFS vs. BFS

DFS:



Depth-First-Search:
Searches as far as possible,
returns when stuck.

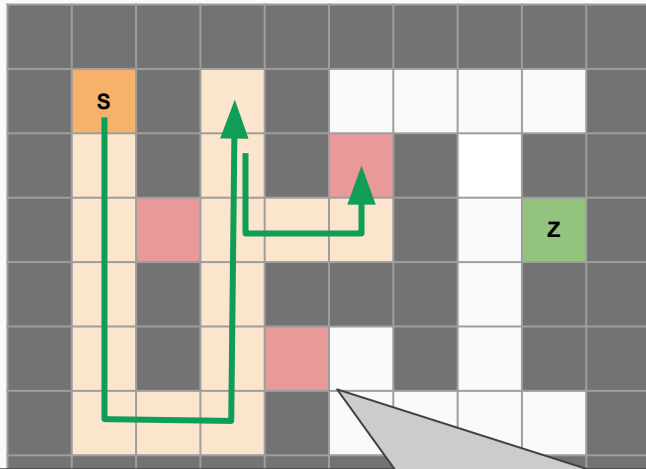
BFS:



Breadth-First-Search:
Searches all paths at the same time.

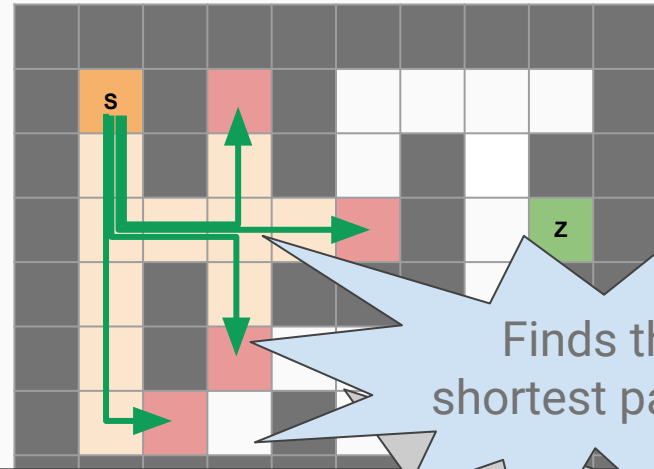
DFS vs. BFS

DFS:



Depth-First-Search:
Searches as far as possible,
returns when stuck.

BFS:



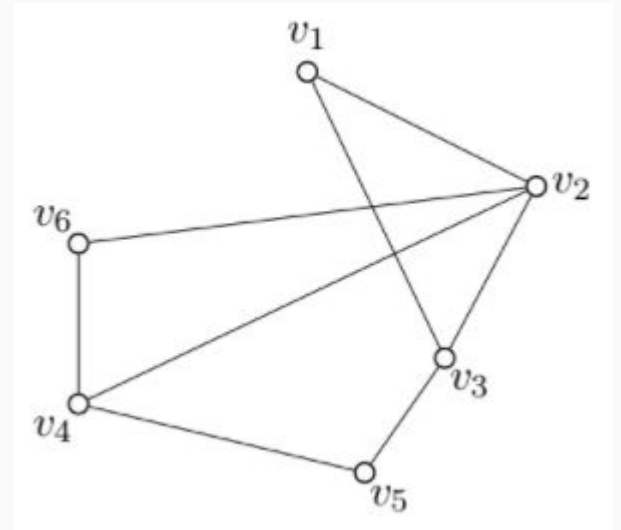
Breadth-First-Search:
Searches all paths at the same time.

Finds the
shortest path :-)

Searching Graphs:

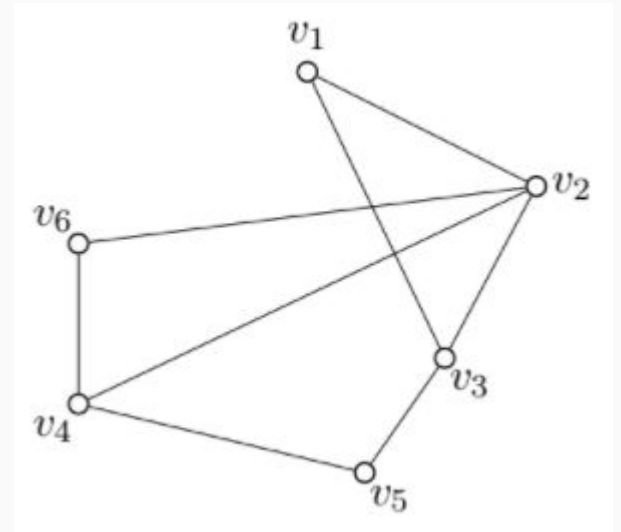
```
mark all vertices not visited  
mark start as visited  
vertices to look at = {start}
```

```
while we still have vertices to look at {  
  take one of them  
  for all its unvisited neighbors n {  
    mark n visited  
    put n into vertices to look at  
  }  
}
```



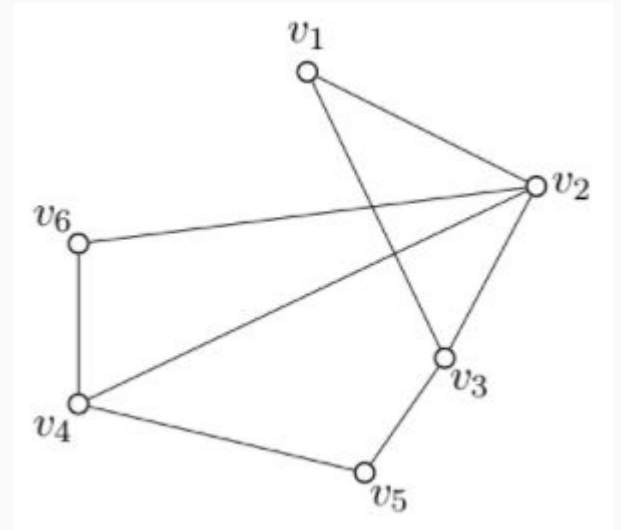
Searching Graphs: DFS

```
vector<int> stack;  
visited[start] = true; stack.push_back(start);  
while !stack.empty() {  
    v = stack.pop()  
    for (int n : a[v]) {  
        if (!visited[n]) {  
            visited[n] = true;  
            stack.push_back(n);  
        }  
    }  
}
```

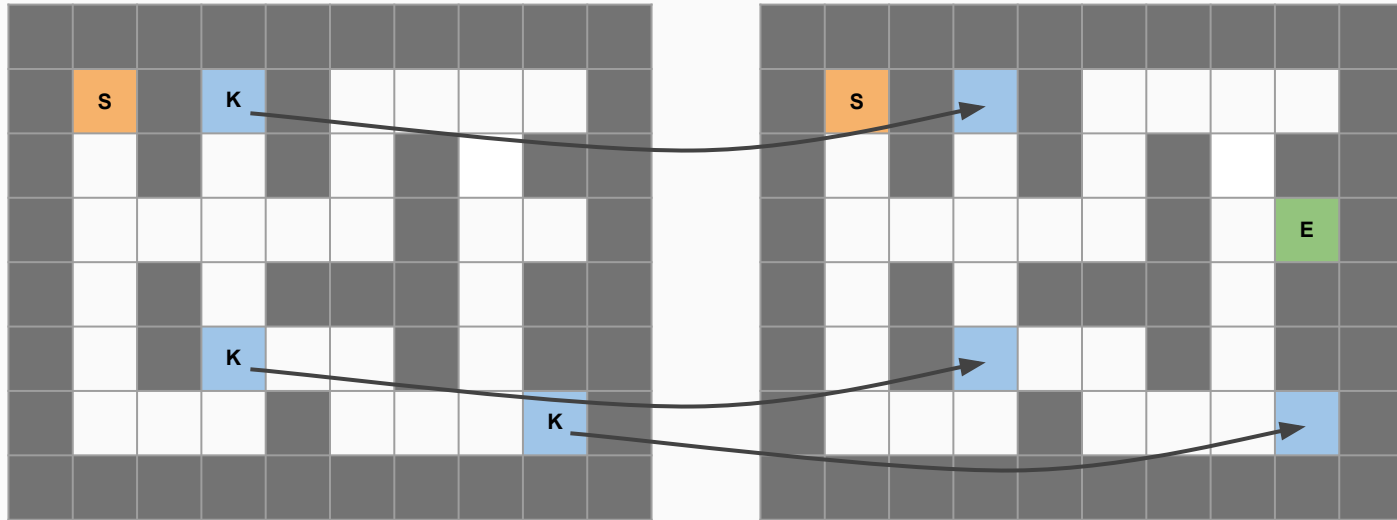


Searching Graphs: BFS

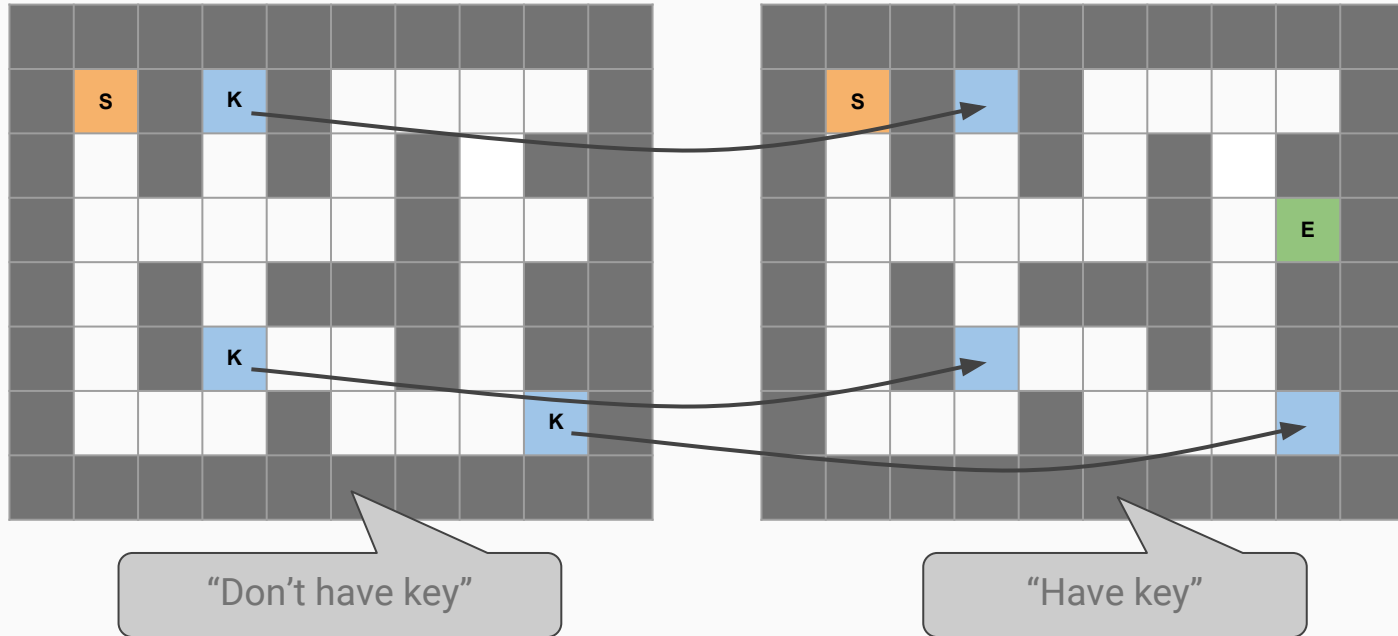
```
queue<int> q;  
visited[start] = true; q.push_back(start);  
while !q.empty() {  
    v = q.pop_front()  
    for (int n : a[v]) {  
        if (!visited[n]) {  
            visited[n] = true;  
            q.push_back(n);  
        }  
    }  
}
```



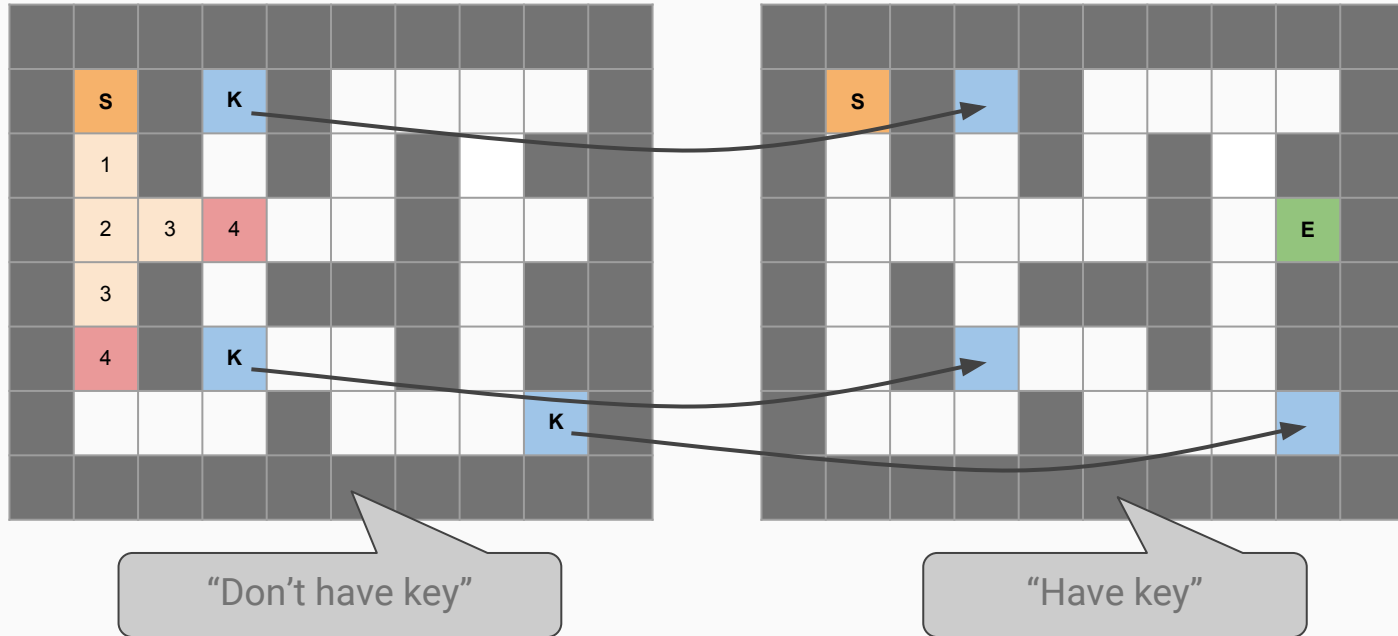
Problem: Shortest Path in a Maze, Key Opens Exit



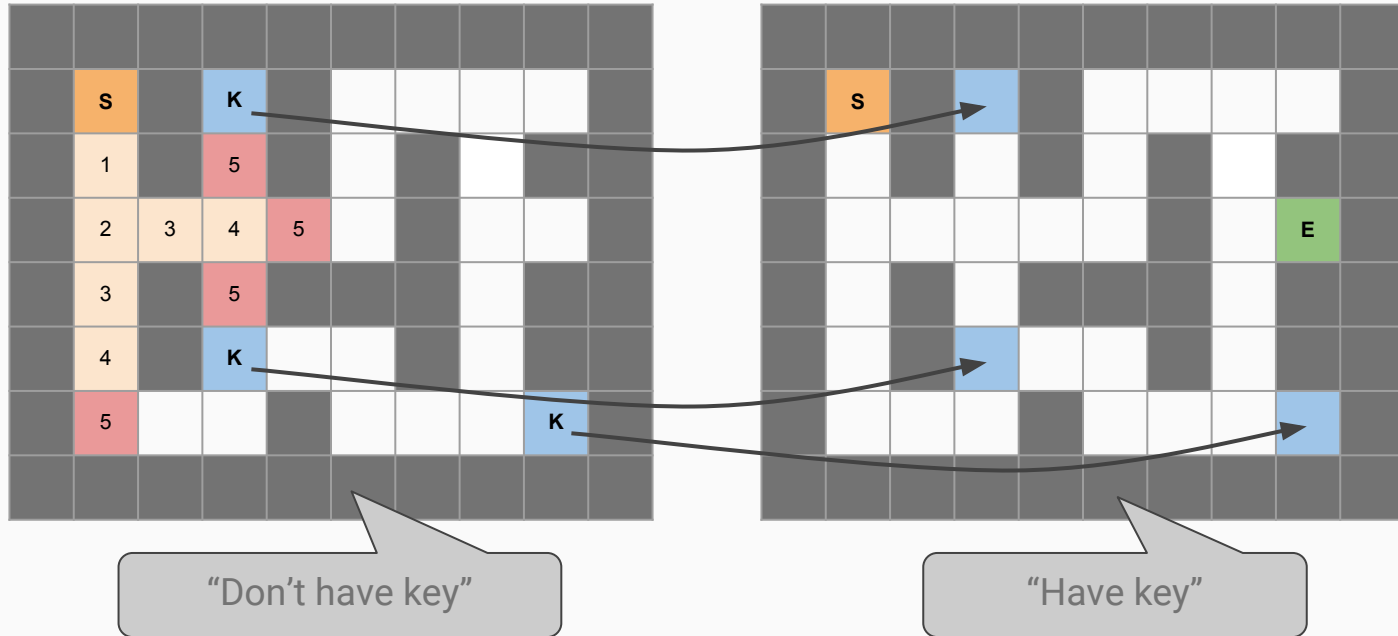
Problem: Shortest Path in a Maze, Key Opens Exit



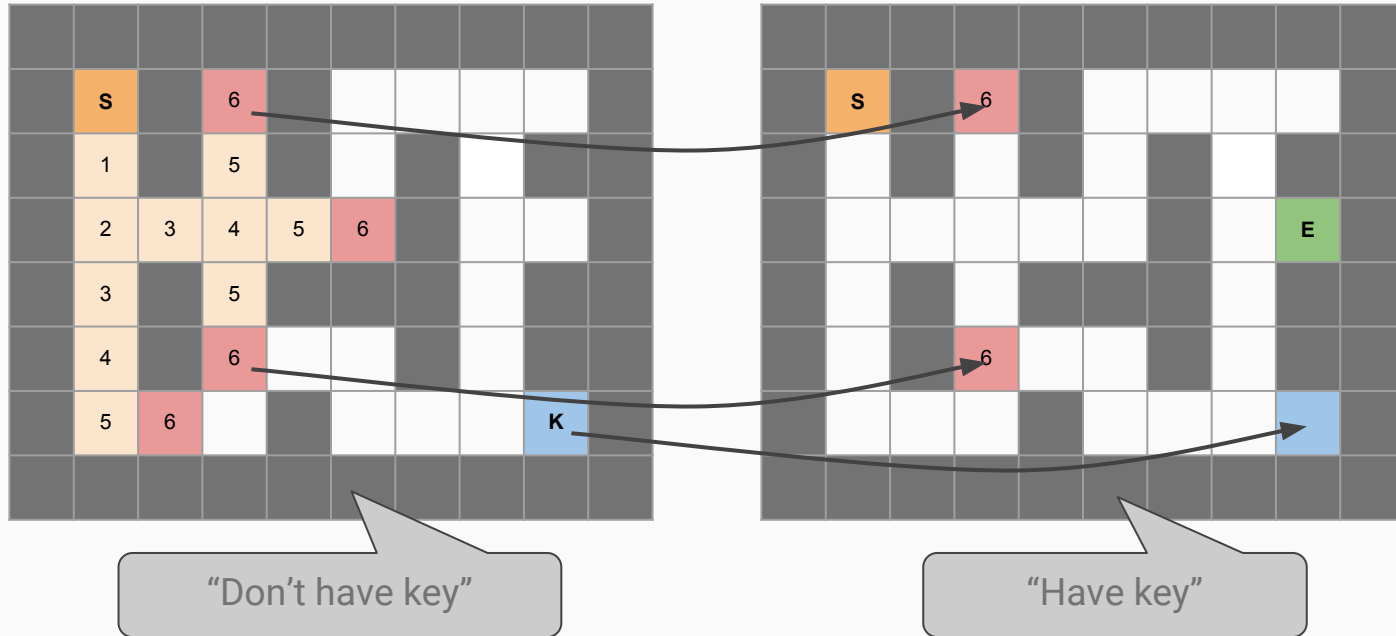
Problem: Shortest Path in a Maze, Key Opens Exit



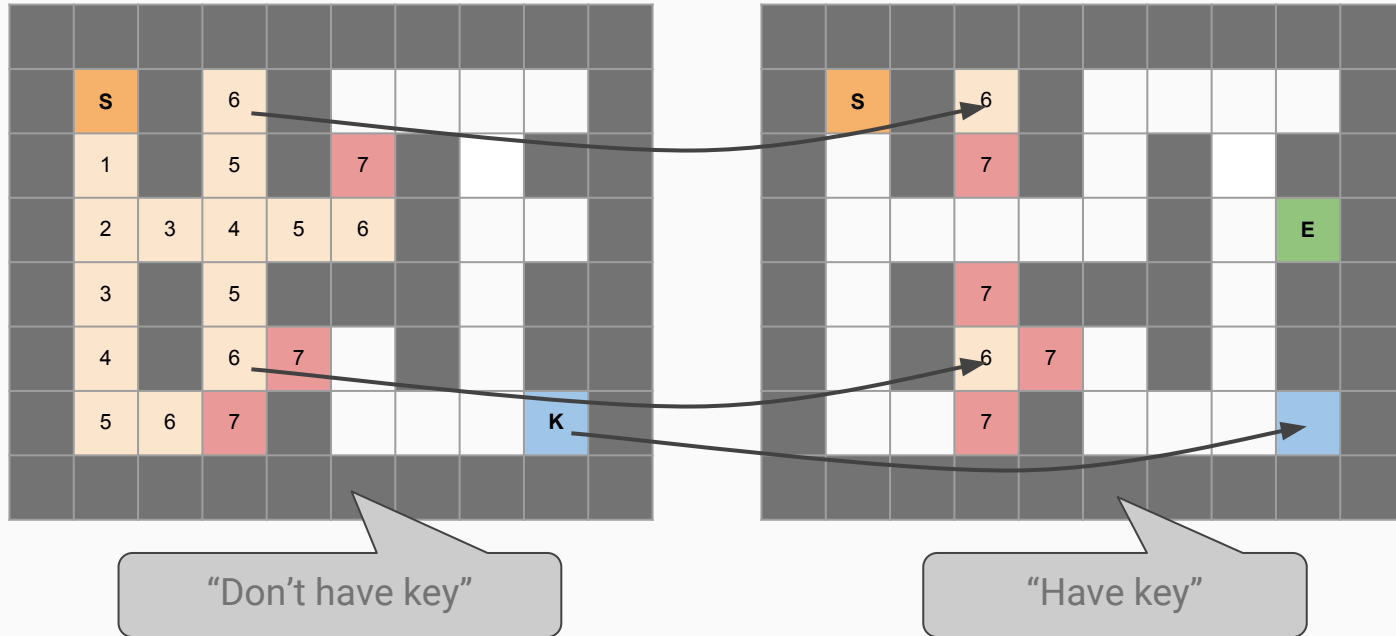
Problem: Shortest Path in a Maze, Key Opens Exit



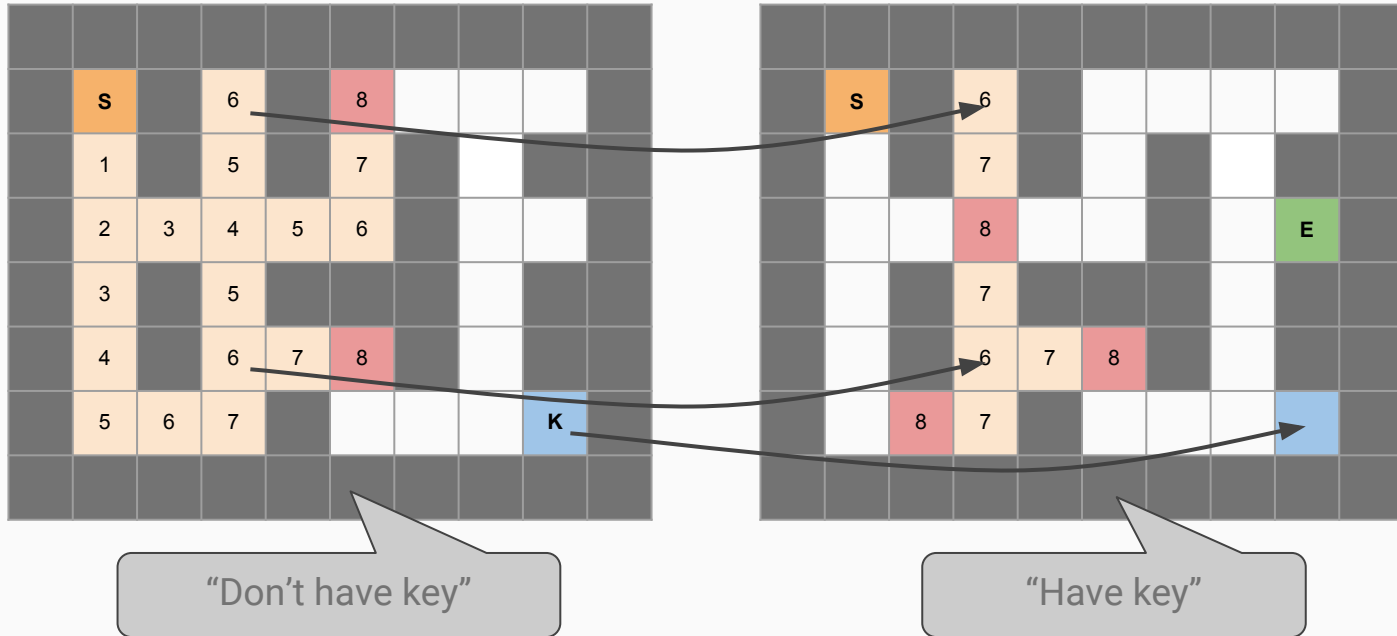
Problem: Shortest Path in a Maze, Key Opens Exit



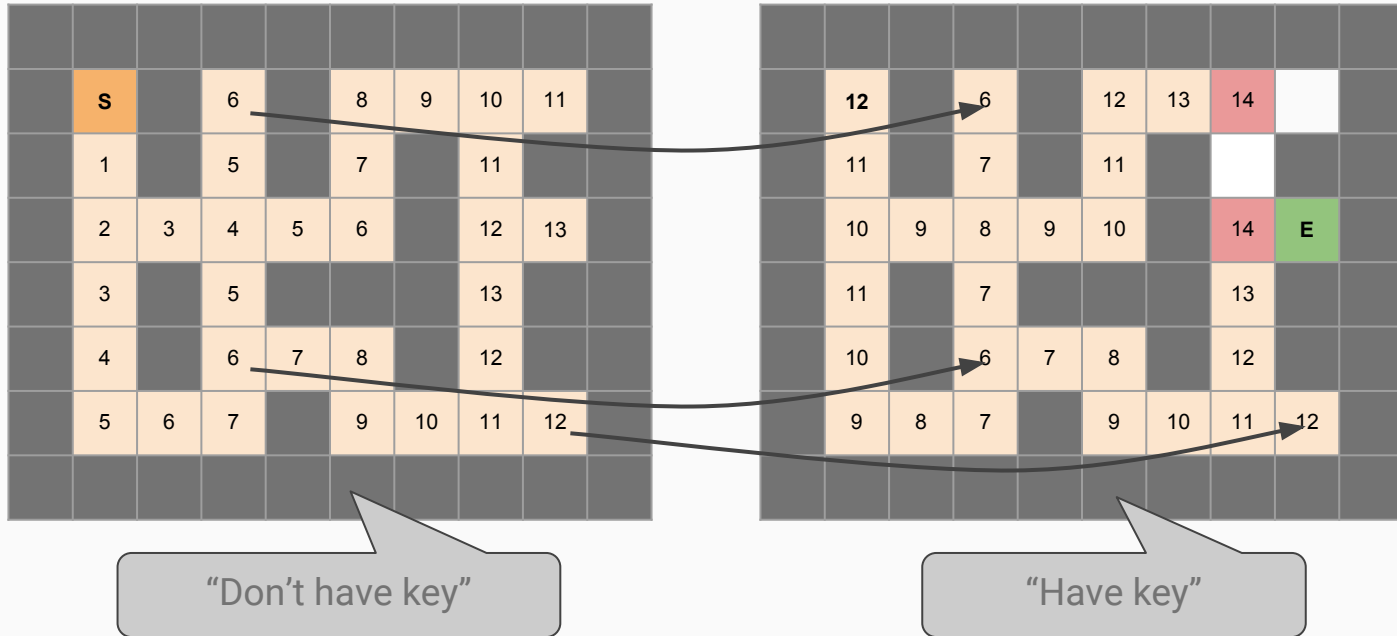
Problem: Shortest Path in a Maze, Key Opens Exit



Problem: Shortest Path in a Maze, Key Opens Exit



Problem: Shortest Path in a Maze, Key Opens Exit



Problem: Shortest Path in a Maze, Key Opens Exit

Have a key?

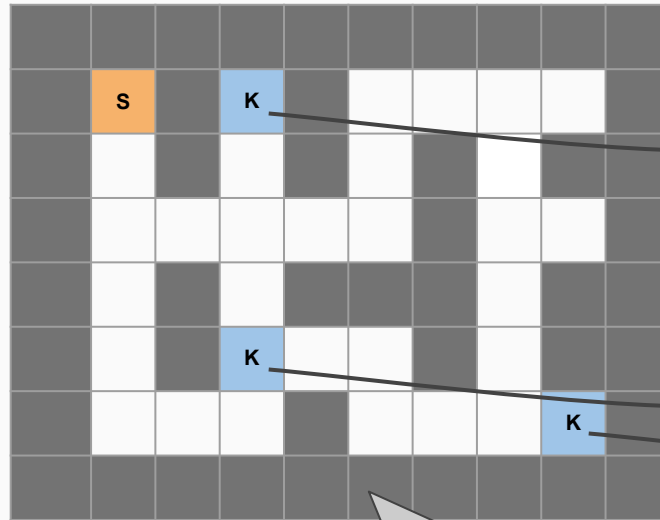
Position: $\langle \text{int}, \text{int}, \text{bool} \rangle$

Start = start_x, start_y, false

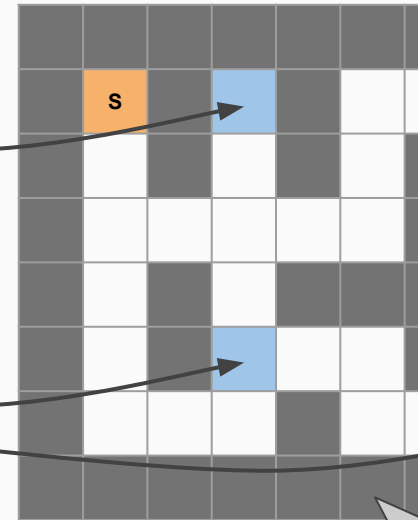
End = end_x, end_y, true

Neighbours of (i,j,k) are:

- $(i, j+1, k \parallel m[i][j+1] == 'K')$,
- $(i, j-1, k \parallel m[i][j-1] == 'K')$,
- $(i+1, j, k \parallel m[i+1][j] == 'K')$,
- $(i-1, j, k \parallel m[i-1][j] == 'K')$,

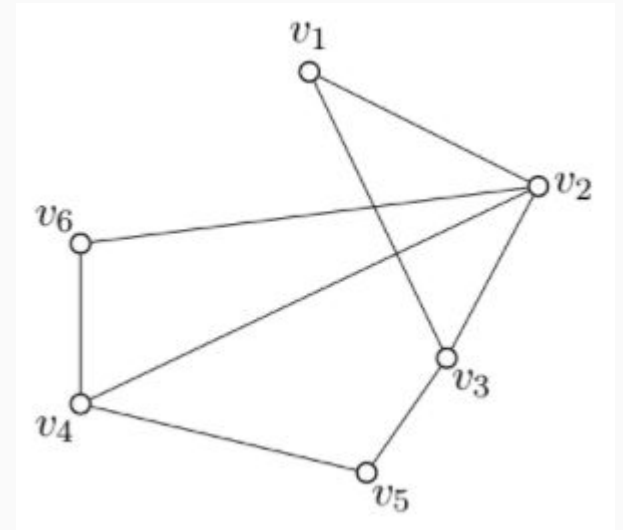


"Don't have key"

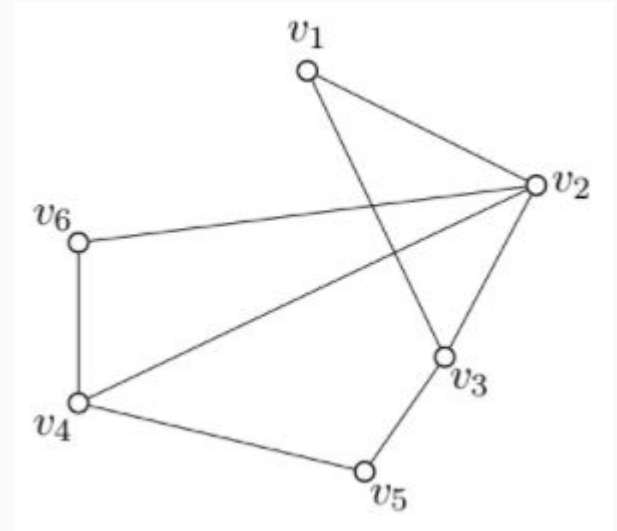


"Have key"

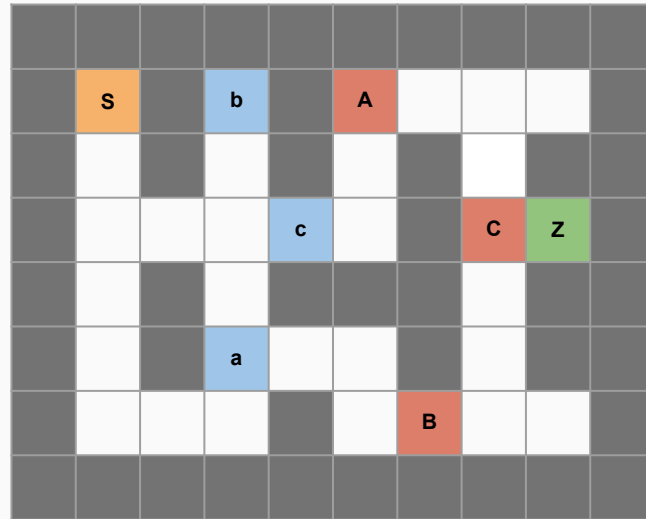
Problem: Shortest Path from A to B



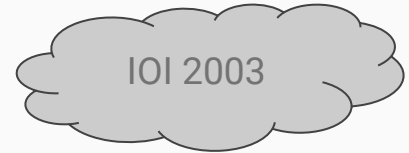
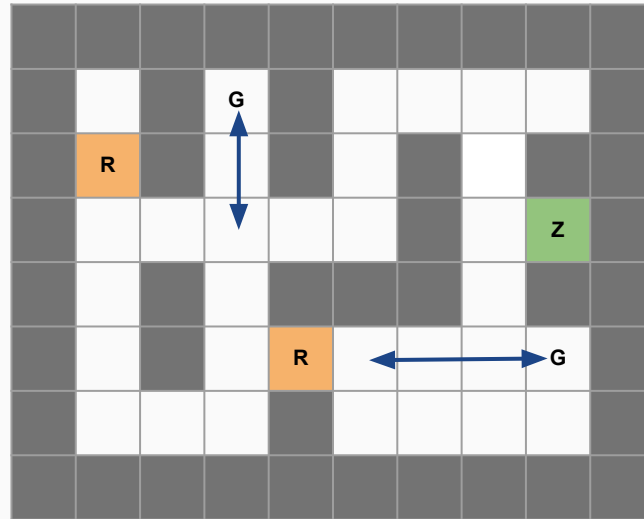
Problem: Shortest Path from A to B of Even Length



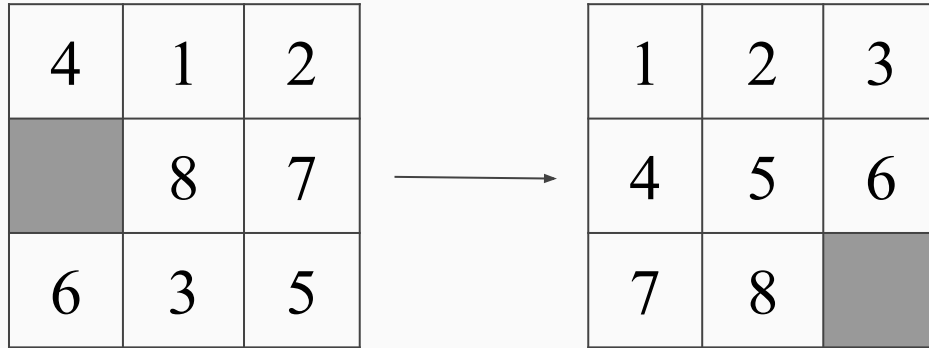
Problem: Shortest Path in a Maze, Keys Open Doors



Problem: Two Robots in a Maze, with Guards



Problem: The 8-Puzzle



Problem: The 8-Puzzle

Still just a BFS!

Position: ???

Image: <https://www.geeksforgeeks.org/wp-content/uploads/image6.png>

Problem: The 8-Puzzle

Still just a BFS!

"412x87635"



Position: string

How to set up array 'visited'?

How to generate all positions?

4	1	2
	8	7
6	3	5

Image: <https://www.geeksforgeeks.org/wp-content/uploads/image6.png>

Problem: The 8-Puzzle

Still just a BFS!

"412x87635"



Position: string

visited = map<string, bool>

Generate new positions
only when needed.

#positions $\leq 9! \sim 360'000$



4	1	2
	8	7
6	3	5

Problem: Cups

Have = Three measuring cups,
with volumes $A, B, C < 200\text{ml}$.

Task = measure K ml with
as few operations as possible.

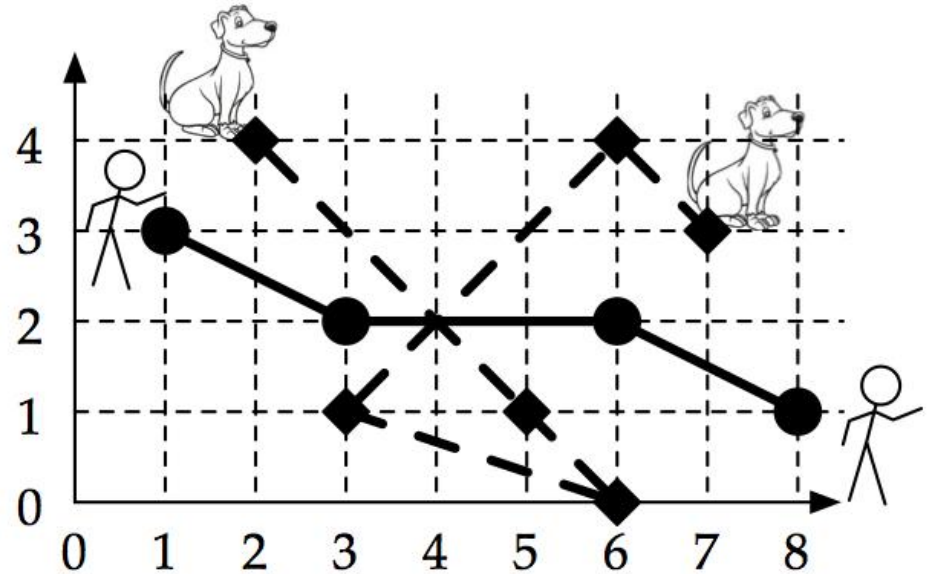
Problem: Dog Walk

Have = Prescribed path for you
and for your dog.

Every second, each of you can

- move to the next point,
- move to the previous point,
- stay put.

Task = find minimum length of
leash to make the walk possible.



Summary

Summary

List of edges:

```
e = vector<pair<int, int>>
```

Adjacency lists:

```
a = vector<vector<int>>
```

Adjacency matrix:

```
a = vector<vector<bool>>
```

**Graphs are
everywhere!**

There are
many other variations.

Summary

Master trick = find the “state space” of the problem.

The state space is a graph, but you do not have to store it explicitly.