

Computability and Computational Complexity

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Introduction

So we get a computational problem. What can we do with it?

- Find a fast algorithm \rightarrow IOI
- Prove there is **no fast algorithm** \rightarrow Complexity theory
- Prove there is **no algorithm at all** \rightarrow Computability theory

Outline

- 1 Introduction
- 2 Computability theory
- 3 Complexity theory

Introduction

We need a formal setting:

- Pick your favourite programming language.
- Program and data can always be converted to a string of bits.

Introduction – problems

But what is a problem, anyway? Examples:

- Given integer, decide if it is prime or composite (**PRIMES**).
- Given **simple graph**, decide if it has a cycle that visits every **vertex** exactly once (**HAMILTON-CYCLE**).
- Given simple graph, decide if it has a cycle that visits every **edge** exactly once (**EULER-CYCLE**).
- Given program A and input x , decide if $A(x)$ stops or runs forever (**HALTING**).

Introduction – problems

Further examples:

- Given set of integers and another integer k , decide if it has non-empty subset with total sum k (**SUBSET-SUM**).
- Given simple graph and k , decide if there is a set of k vertices that “touches” all edges (**VERTEX-COVER**).
- Given n tasks that take time t_1, \dots, t_n and a deadline T , decide if you can divide them between two processors such that processing is finished before the deadline (**JOB-SCHEDULING**).
- Given polynomial with integer coefficients $p(x_1, \dots, x_n)$, decide if there exist integer coordinates z_1, \dots, z_n such that $p(z_1, \dots, z_n) = 0$ (**POLY-INT-ZERO**).

Introduction – problems

To sum up:

- We are interested in **decision problems**, with input and “yes”/“no” answer.
- There is usually a natural notion of **input size** (useful later).
- **Worst-case analysis**: we want programs that are correct on every input.

Exercise

Q: What about non-decision problems?

A: Handled by standard tricks. For example, take VERTEX-COVER. How to compute size of smallest VC if we can decide if there exists VC of size k ? How to compute smallest VC if we can compute size of smallest VC?

Amazing fact: there are problems for which no algorithm exists!

Halting problem

Given program A and input x , decide if $A(x)$ stops or runs forever (**HALTING**).

- For sure we can run $A(x)$ and see if it stops. . .
- But how long do we wait?
- Maybe if the program loops we can detect it. . . But have you ever heard of **busy beavers**?

For some nasty programs **runs forever** is a better phrase than **loops forever**.

Proof of undecidability

Proof by contradiction! Assume there exists program B that solves halting problem on every input.

Remember that both programs and inputs are just strings of bits. We can make an (infinite) list of them all:

$\epsilon, 0, 1, 00, 01, 10, 11, 000, 001, \dots$

Assuming this order we can interpret this list as enumeration of all possible programs A_1, A_2, \dots or of all possible inputs x_1, x_2, \dots

Proof of undecidability

With that in mind we write the following program:

```
C(x_i) {  
    if (B(A_i, x_i)) {  
        run forever;  
    } else {  
        stop;  
    }  
}
```

Proof of undecidability

Let us make a huge (infinite) 2D table. Rows are inputs, columns are programs. In row x_i and column A_j we put 1 if $A_j(x_i)$ stops, and 0 otherwise:

	A_1	A_2	A_3	A_4	\dots
x_1	1	0	1	1	\dots
x_2	1	0	1	0	\dots
x_3	1	1	1	1	\dots
x_4	1	0	1	0	\dots
		\dots			

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x_2	1	0	1	0	\dots
x_3	1	1	1	1	\dots
x_4	1	0	1	0	\dots
		\dots			

C	A_1	A_2	A_3	A_4	\dots
x_1	1/0	0	1	1	\dots
x_2	1	0/1	1	0	\dots
x_3	1	1	1/0	1	\dots
x_4	1	0	1	0/1	\dots
		\dots			

C cannot be any of $A_1, A_2, \dots!$ Therefore, C cannot exist.
Therefore, B cannot exist.

This is called the **diagonal method**.

Some comments

This sounds like cheating, right?

Exercise

We just showed that every program fails to solve HALTING on *at least one input*. Show that every program fails to solve HALTING on *infinite number of inputs*.

Fact

Q: One more of example programs is undecidable. Which one? A: POLY-INT-ZERO

Preliminaries

To prove there is no fast algorithm for a problem, we need to define “fast” first.

- Assign **size** n to every input.
- In principle size should be a number of bits used to describe the input, but it is ok if it is another (polynomially related) notion.
- **Worst-case analysis**: maximum running time of the algorithm over all inputs of size n .
- $O()$ -notation: constant factors and low-order terms ignored:
 $100n^2 + 10n = O(n^2)$.

Running times

Assume you have an algorithm that runs in time t for inputs of size n .

- Good: polynomial time, e.g., $O(n^2)$ — to compute input of size $2n$ in time t you need four times faster machine.
- Bad: exponential time, e.g.: $O(3^n)$ — to compute input of size $n + 1$ in time t you need three times faster machine.
- Polynomial time is $n^c = 2^{c \log n}$. Exponential time is $c^n = 2^{(\log c)n}$. There is a lot of functions “in between”, e.g., $n^{\log n} = 2^{\log^2 n}$, $2^{\sqrt{n}}$, etc. They are also “bad”.

Running times

Problem

Q: What about runtimes $10^{20} \cdot n$, or $10^{-3} \cdot (1.000001)^n$?

P vs. NP

P is a class of all problems that have algorithms that run in $O(n^c)$ for some c . For example, PRIMES has an algorithm running in $O(n^6)$, hence it is in P.

Another very important class is called NP. These are problems that are “easy-to-verify”.

Definition of NP

The inputs for each problem can be divided into “yes”-instances and “no”-instances.

A problem is in NP if there exists an efficient (polynomial-time) way of verifying instances, such that:

- For each “yes”-instance there exists *some* proof.
- For each “no”-instance there is *no* proof.

What is a “proof”? A bitstring. How do you verify it? By a program that takes proof as additional input.

Definition of NP – example

Given **simple graph**, decide if it has a cycle that visits every **vertex** exactly once (**Hamilton cycle**).

A proof is a cycle in the graph and we verify it by checking if it is a Hamilton cycle.

Definition of NP – example

Given set of integers and another integer k , decide if it has non-empty subset with total sum k (**subset sum**).

A proof is a subset and we verify it by checking if its sum is k .

Definition of NP – exercises

Exercise

- Is primality testing in NP?
- Show that $P \subseteq NP$.
- Is halting problem in NP?

P vs. NP

Problem

Are P and NP equal? Good question.

But why is the answer important?

NP-completeness

So far we do not have high hopes for proving either $P = NP$ or $P \neq NP$.

But we can prove this: there exists a huge range (hundreds) of problems that are “NP-complete”.

- If $P = NP$, *all* those problems are in P .
- If $P \neq NP$, *all* of them are outside P .

In particular, Hamilton cycle, subset sum, vertex cover and job scheduling are all NP-complete.

Proving NP-completeness

How do you prove NP-completeness for a problem L ?

- First, show $L \in \text{NP}$. That way $P = \text{NP} \implies L \in P$.
- Second, take some problem L' that you already know is NP-complete and show that $L \in P \implies L' \in P$ (in a sense you show that L' is not harder than L).

Problem

Q: But you need to start with the first NP-complete problem?
How do you get it?

A: Well... somehow. It is called **Cook's theorem**.

Proving NP-completeness – example

Example. Recall:

- Given simple graph and k , decide if there is a set of k vertices that “touches” all edges (**VERTEX-COVER**).
- Given set of integers and another integer k , decide if it has non-empty subset with total sum k (**SUBSET-SUM**).

Assume we know that VERTEX-COVER is NP-complete. How to show that SUBSET-SUM is NP-complete?

Does SUBSET-SUM \in NP? Yes!

Proving NP-completeness – reductions

To show: $\text{SUBSET-SUM} \in \text{P} \implies \text{VERTEX-COVER} \in \text{P}$.

How to prove this step? Using a **reduction**.

Assume you have a program A that puts SUBSET-SUM in P.
Write a program (**reduction**) that will call A as subprocedure and (efficiently) solve VERTEX-COVER.

Reduction VERTEX-COVER \leq_p SUBSET-SUM

Given G with n vertices and m edges and $0 \leq k < n$ the reduction constructs SUBSET-SUM instance as follows:

There are $n + m$ numbers, each of them with $m + 1$ digits *in base n* .

Reduction VERTEX-COVER \leq_p SUBSET-SUM

For each vertex u we construct number s_u :

	d_0	d_1	d_2	\dots	d_e	\dots	d_m
s_u	1	0	1	\dots	1	\dots	0

where d_0 is always 1 and $d_e = 1$ if and only if u is one of the endpoints of e .

For each edge e we construct number t_e :

	d_0	d_1	d_2	\dots	d_e	\dots	d_m
t_e	0	0	0	\dots	1	\dots	0

with a single 1 at digit e .

Reduction VERTEX-COVER \leq_p SUBSET-SUM

In total, we want:

+	d_0	d_1	d_2	\dots	d_e	\dots	d_m
\dots							
s_u	1	0	1	\dots	1	\dots	0
\dots							
t_e	0	0	0	\dots	1	\dots	0
\dots							
$k' =$	k	2	2	\dots	2	\dots	2

Reduction $\text{VERTEX-COVER} \leq_p \text{SUBSET-SUM}$

We (efficiently) constructed a SUBSET-SUM instance from VERTEX-COVER instance.

If we prove:

- “yes”-instance of VERTEX-COVER is always mapped to “yes”-instance of SUBSET-SUM.
- “no”-instance of VERTEX-COVER is always mapped to “no”-instance of SUBSET-SUM,

we are done! We can solve VERTEX-COVER by mapping it to SUBSET-SUM and returning whatever SUBSET-SUM algorithm returns.

Exercise

Prove mapping property from the previous slide.

Congratulations! You proved a problem NP-complete. There is a whole theory of various smart (“gadget”) reductions like that.

P vs. NP – some consequences

- 1 If $P = NP$:
 - Huge progress in solving problems.
 - “Creativity” not significantly harder than “verifying”.
 - Almost all cryptography used in practice is broken.
 - 2 If $P \neq NP$:
 - Cryptography is provably safe.
 - Randomized algorithms do not give significant speedup.
- Both bullet points require stronger assumptions than $P \neq NP$.

What else?

Oracles, circuits, randomized algorithms, space complexity, approximation algorithms, interactive proofs, quantum algorithms, cryptography, communication complexity, natural proofs. . .

THANKS!